

Automated Driving Systems



Pedestrian Traffic Accident Reduction

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◆ Reduce pedestrian accidents with automated driving and IoT

(1) Survey and analysis of accident circumstances (Institute for Traffic Accident Research and Data Analysis [ITARDA])

- Classification of all accident patterns and trend analysis

→ Ascertainment of the actual circumstances of pedestrian accidents and study of countermeasures

(2) R&D on technologies for estimating accident reduction effects (Japan Automobile Research Institute [JARI])

- Simulation technologies that recreate traffic environments based on a multi-agent system

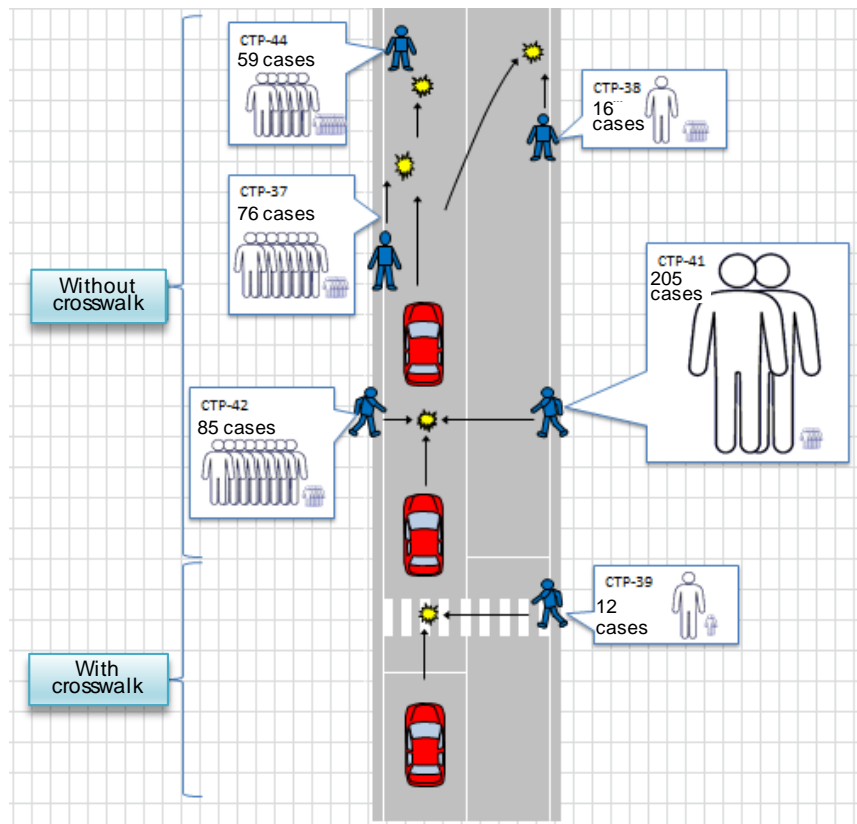
→ Prediction of accident-reduction effects according to system performance

(3) R&D on vehicle-to-pedestrian communication systems (Panasonic)

- Mutual cognizance of other's presence by pedestrians and vehicles through intercommunication

→ Reduction of accidents caused by cognitive errors, which account for a large portion of pedestrian accidents

◆ Classification of accidents into patterns (3 or more fatalities: 256 patterns)



- Extraction of pedestrian accidents and analysis of contributing factors
- Envisioning of possible countermeasures for each factor

Example: Ignoring of traffic lights while walking
→ Awareness activities

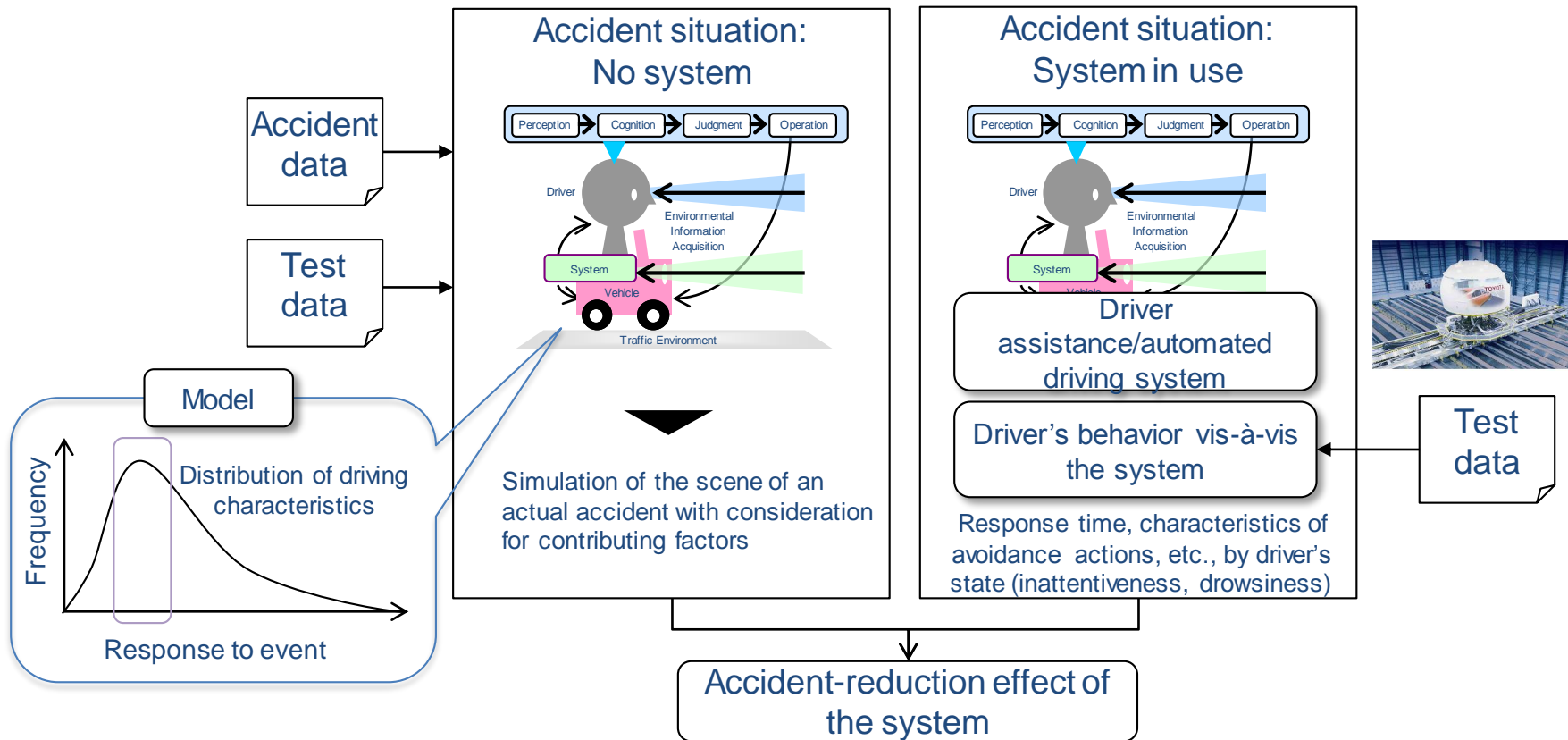
- “Possible that accident could have been avoided with awareness” (e.g., inattention ahead, failure to confirm safety, etc.)

64 patterns, 1,043 out of 1,305 cases (80%)

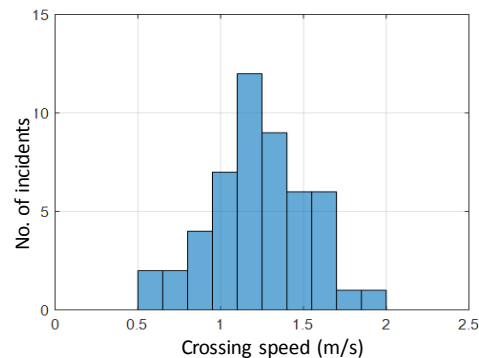
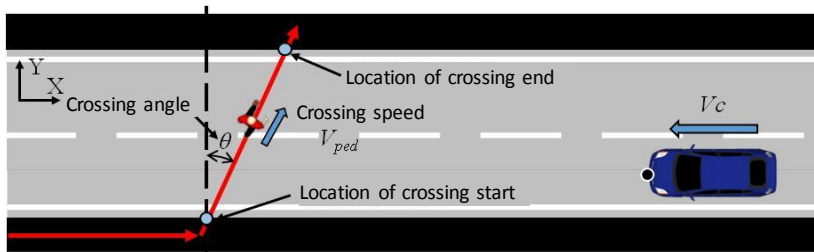


Support for mutual cognizance using vehicle-to-pedestrian communication

◆ Recreation of traffic environments and accidents through multi-agent simulation



- ◆ Construction of a pedestrian crossing model using fixed-point observations and experiments



- ◆ Using simulation makes it possible to replicate accidents that involved pedestrians.



Validity studies are currently underway.

- ◆ The system supports mutual cognizance of presence through direct communication at a dedicated ITS frequency (760 MHz) between pedestrians' terminals and vehicles.



- ◆ Alerts should be issued only in cases where there is a strong possibility of contact between a vehicle and pedestrians.

- The system says “Be careful,” but the pedestrian is way over in the opposite lane.



➔ Pedestrian locations must be ascertained with high precision.

High-precision positioning technology

- The pedestrians are safe on the sidewalk. I wish the system would stop saying “be careful” all the time.



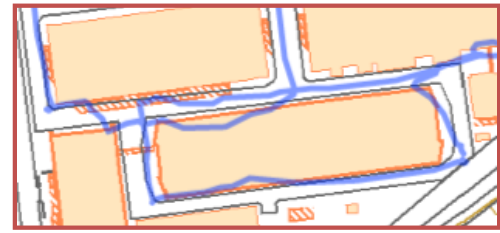
➔ Ascertaining danger to pedestrians and the vehicle is required.

Technology for estimating cross-over probability

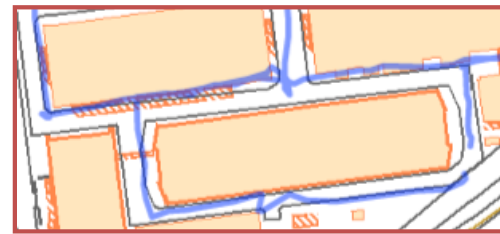
◆ Ensuring a certain degree of accuracy even in adverse environments by combining numerous technologies

- (1) Eliminating positioning errors caused by reflected satellite waves
- (2) Pedestrian dead reckoning (PDR)
- (3) Correction by Doppler velocity

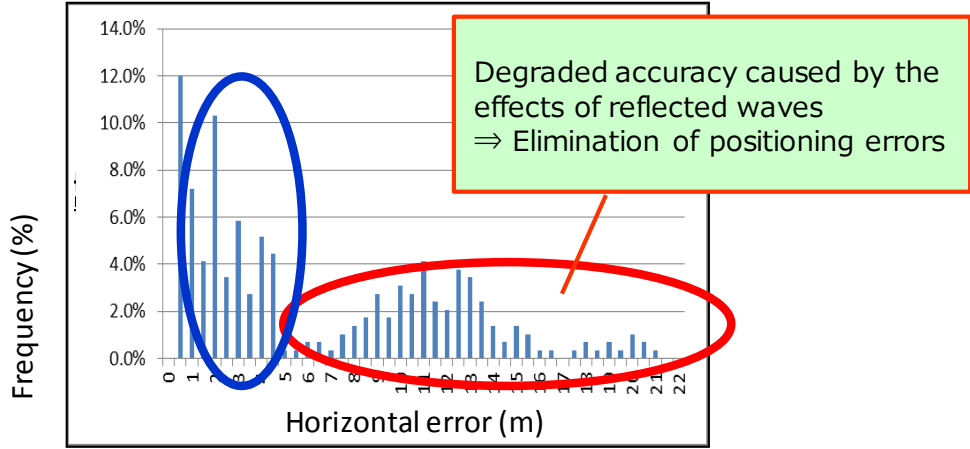
(±20m → ±5m)



Elimination of satellite positioning error only



Corrective additions with PDR, etc.

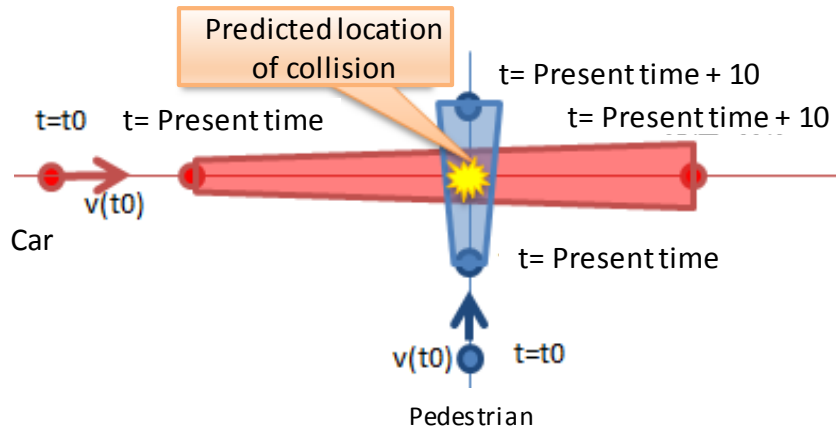


- ◆ Development of technology to estimate pedestrians' states for assessing the pedestrian environment



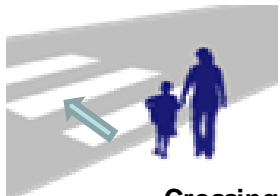
Example: Determination that a pedestrian is walking on a delineated sidewalk from map information and high-precision pedestrian positioning technology

- ◆ Construction of an algorithm that predicts collisions



Estimation of cross-over probability

Situations requiring assistance



Crossing



Right turn at intersection



Obstructed view



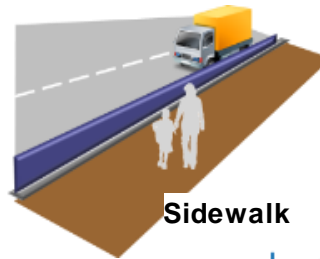
Walking on roadway



Left turn at intersection

Aggregation into five situations from the pattern analysis of accident circumstances

Situations not requiring assistance



Sidewalk



Inside vehicle



Inside building



On pedestrian bridge



On or below elevate structure

Establishment of five situations from the Report of the Survey on Time Use and Leisure Activities

Oct. 2017

Jan. 2018

Apr.

Jul.

Oct.

Jan. 2019

Mar./E

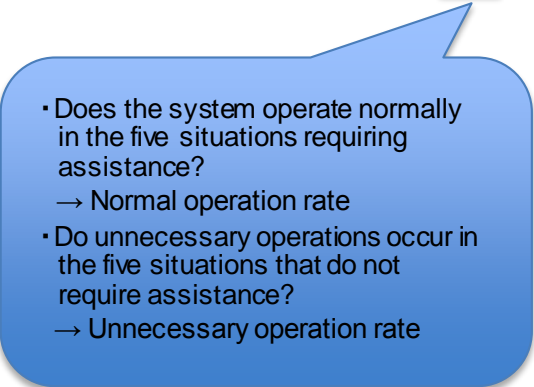


Study of test location



Phase 1: System operation verification

☆ Checking of the system's operations in an actual traffic environment

- 
- Does the system operate normally in the five situations requiring assistance?
→ Normal operation rate
 - Do unnecessary operations occur in the five situations that do not require assistance?
→ Unnecessary operation rate

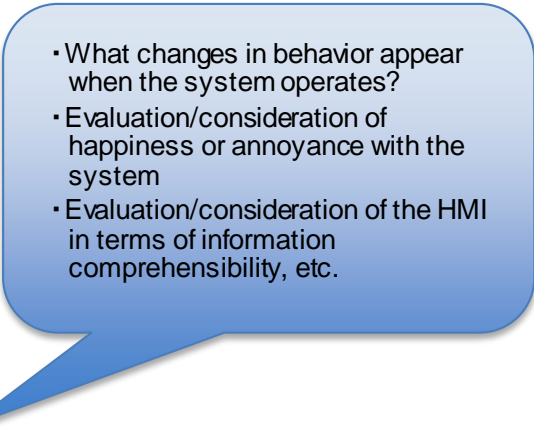


System improvement



Phase 2: System effects verification

☆ Checking of the system's effects in an actual traffic environment using numerous participants

- 
- What changes in behavior appear when the system operates?
 - Evaluation/consideration of happiness or annoyance with the system
 - Evaluation/consideration of the HMI in terms of information comprehensibility, etc.

■ Situations requiring assistance

(1) Pedestrian road crossing



(3) Right turn at intersection



(5) Road without sidewalk



(2) Passing at intersection



(4) Left turn at intersection



Odaiba

■ Situations not requiring assistance

(6) In vehicle
- Vehicle

(7) In building
- Aqua City, etc.

(8) On pedestrian bridge



(9) Sidewalk



(10) Elevated crossing



Pedestrian test terminal



Wireless communications device, battery, high-precision localizing device, and other equipment integrated into a backpack-like package

Vehicle test terminal

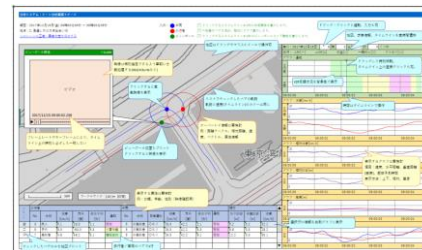


Vehicle installed with a wireless communications device, interior and exterior cameras, CAN logger, etc.

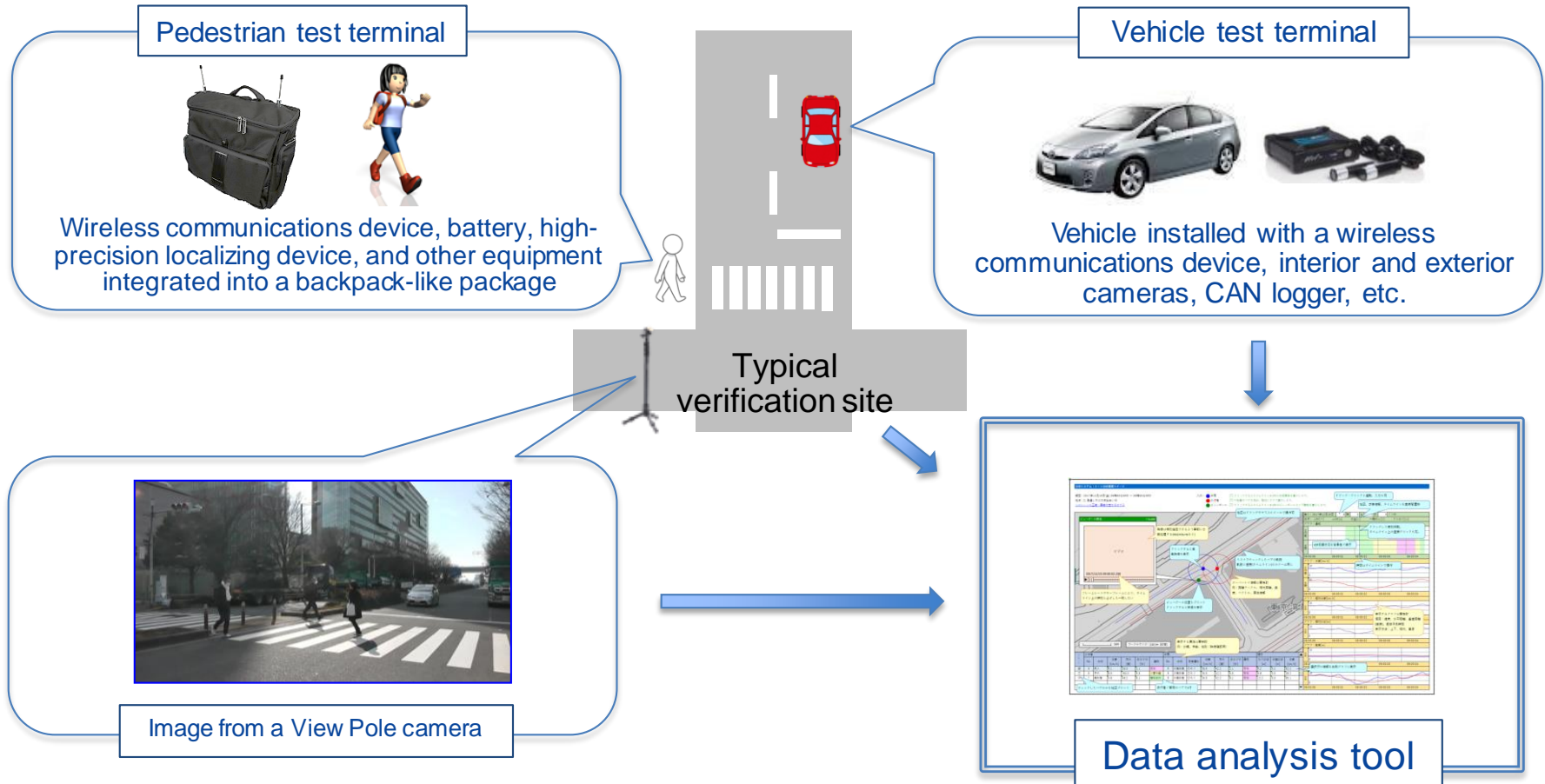
Typical verification site



Image from a View Pole camera



Data analysis tool



SIPHokousya

日時: 2016年10月14日(金)
 時刻: 18時45分22秒~18時45分32秒
 シーン: 1/1 (1/1) 歩行者の位置情報

歩行者ID: 20
 速度: 1.2

歩行者 (歩行者)
 速度 (歩行者)
 ビューポート

歩行者 (歩行者)
 速度 (歩行者)

歩行者
 速度

2016年10月14日 18:45:22 18:45:27 18:45:32 18:45:37 18:45:42 18:45:47 18:45:52

歩行者速度 (m/s)

歩行者速度 (m/s)

歩行者	名前	性別	年齢	性別	速度 (m/s)	方向 (度)	歩数	方向	日時	速度 (m/s)	方向 (度)	歩数	歩数	速度 (m/s)
※	※	20	成人	男	3.4	152.3	2	歩行者	あり	0.3	17.0	17.8	2.4	3.8

18:45:22 18:45:27 18:45:30 18:45:37 18:45:42 18:45:47 18:45:52

歩行者速度 (m/s)

歩行者速度 (m/s)

13:29 2016/10/14

SIPHokousya

a6844@n-koel.co.jp



0:12 / 0:29



SIPHokousya

URL: https://siphokousya.jp/scene/detail/1102

日時: 2018年02月13日(水)
 時刻: 17時01分02秒~17時01分32秒
 シーン: 03-1:交差点右折(信号有)

歩行者NR: 31
 車両NR: 3

歩行者 (選択中) 歩行者 (非選択)
 車両 (選択中) 車両 (非選択)
 ビューボール

警報 存在通知
 注意喚起 交差点通知
 情報提供

このシーンの分析結果を保存する

2018年02月13日 17時01分32秒 0 走り

歩行者
 車両

歩行者速度 [m/s]

車両速度 [m/s]

表示		歩行者				車両				相対				
グラフ	軌跡	NR	分類	性別	速度 [m/s]	方角 [度]	NR	分類	日供運転	速度 [m/s]	方角 [度]	水平距離 [m]	前後距離 [m]	速度 [m/s]
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	31	成人	女	0.7	93.9	3	非乗客者	あり	0.0	238.4	27.6	9.1	0.7

Windows Taskbar: 11:35 2018/02/24



- End of this fiscal year
 - Analysis of test data and derivation/consideration of results
 - Arrangement of issues identified in the test and consideration of ways to deal with them
 - Identification of points for system improvement

- Next fiscal year
 - System improvements for Phase 2
 - Study of details concerning Phase 2 field operational test methods and preparation of a test plan
 - Phase 2 test
 - Summary



Thank you