

Visualization of the traffic accident reduction effect -Improvement of simulation accuracy-



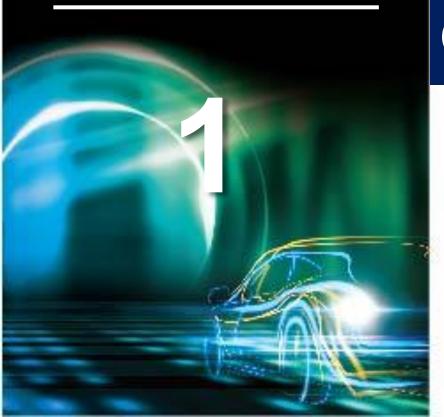
Japan Automobile Research Institute



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Overview

Purpose of this project

[Government policy]

- To put vehicles with Level 2 driver assistance system into practical use on ordinary roads (in 2020)
- To put Level 3 automated vehicles into practical use on highways (in 2020)
- To put Level 4 automated vehicles into practical use on highways (around 2025) etc.

[Society's expectations]

Expectations are rising for the practical application and spread of automated driving technology and driving assistance technology.

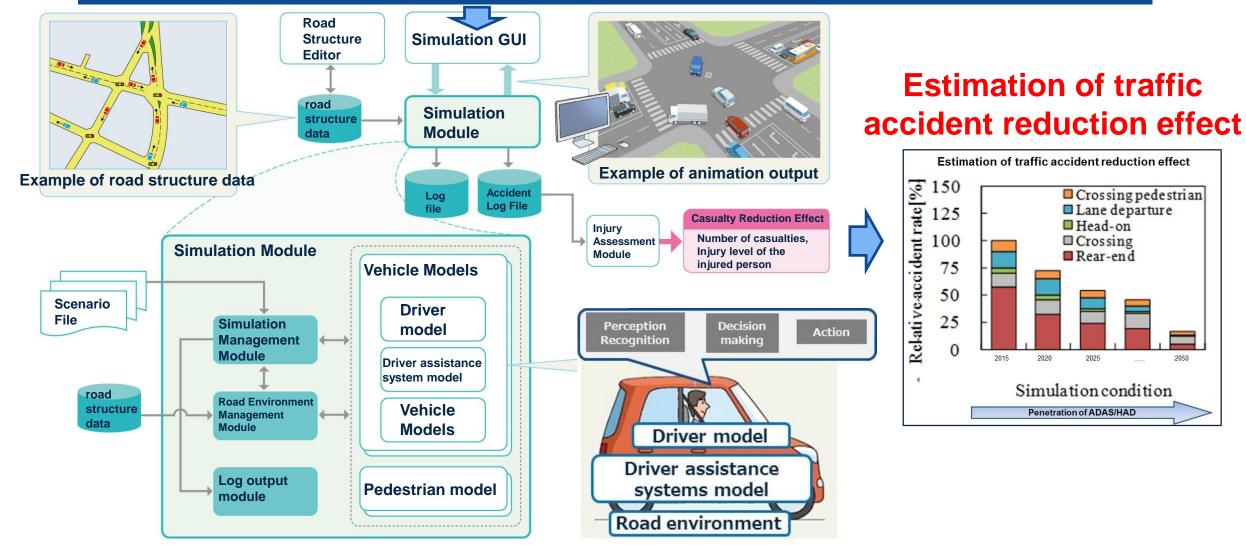
[Purpose of this project]

Fostering social acceptance is necessary for the smooth implementation of automated vehicles and vehicles with driver assistance system in society

In this project, we use a traffic flow simulation to estimate the effect of traffic accident reduction according to the prevalence of automated vehicles and vehicles with driver assistance system.

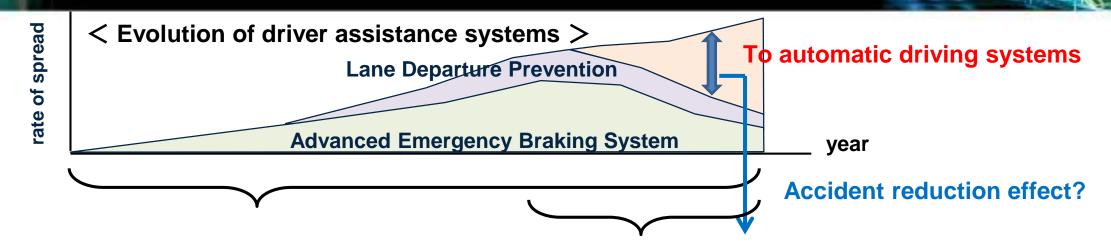
Overview of the entire simulation

Parameters for assumptions (models, dissemination scenarios, etc.)



Positioning of the simulation

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Existing Simulation	SIP Development Simulation
Traffic accident scene reproduction	Multi-agent traffic environment reproduction
For product Development: Competitive area (sensor specifications and control logic)	For policy making : cooperative area ⇒ Strategies for the popularization of automated driving
Micro Simulation (Reproduce a limited place and time)	Macro Simulation (Assume all areas and times)
Traffic participants act according to the predetermined scenario	 Multi-agent Each traffic participant behaves independently and influences each other Error behaviors such as looking aside are also implemented. (Causes of accidents)

Project summary



SIP Phase 1 (2015~2018)	SIP Phase 2(2019~2020)
"Development and substantiation of simulation technology for estimation of detailed traffic accident reduction effects"	"Visualizing the Effects of Traffic Accident Reduction "
 Establish simulation technology Develop <u>behavioral models</u> for traffic participants Validation of the simulation technology (Preconditions are tentatively defined) 	Improvement of simulation accuracy ①Enhance the accuracy of the behavioral models ②Establish preconditions

(1)Enhance the accuracy of the behavioral models

Expand the pedestrian behavior model and establish a new bicycle behavior model

2Establish preconditions

- A. Set dissemination scenarios (*)
- **B.** Set signal indication and traffic regulation information
- **C.** Pedestrian and bicycle models and traffic settings
- **D. Set speed information**

(*)From the "Study of the Impact of Automated Driving on Reducing Traffic Accidents and on Others"



Research in the SIP Phase 1 project

Research in the SIP Phase 1 project

① Development of Multi-Agency Traffic Environment Simulation

② Building a behavioral model for traffic participants

Driver Model

Driving process, driver error, and parameter settings based on driver attributes

Pedestrian Model

model pedestrian behavior based on fixed point observations and experiments

Automatic driving system model

Set parameters such as sensor recognition range and control specifications

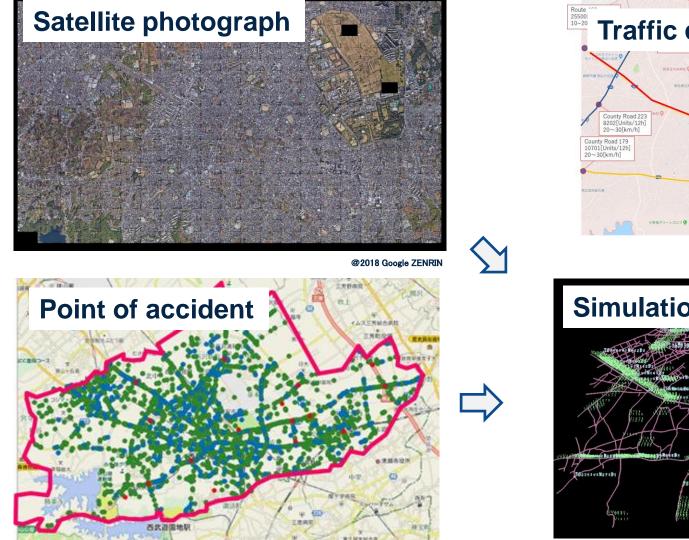
③ Validation of the developed simulation technology

•Selection of model areas (one each for large cities, local cities and depopulated areas)

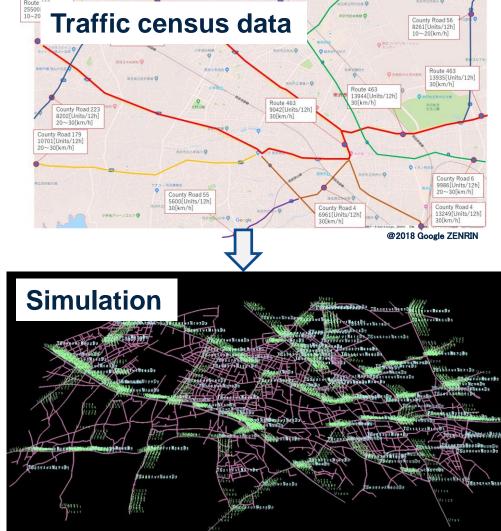
•Confirmation of reproducibility of traffic flows and accidents in the model areas (Compare actual traffic volume and traffic accident statistics with simulation results)

(4) Calculation of reduction effects on a nationwide scale based on tentatively defined preconditions

(Reference) Large city : Simulation image of Tokorozawa City







SI

Major road networks in each model area were built to reproduce traffic flows and traffic accidents.



Research in the SIP Phase 2 project

Project summary



SIP Phase 1 (2015~2018)	SIP Phase 2(2019~2020)
"Development and substantiation of simulation technology for estimation of detailed traffic accident reduction effects"	"Visualizing the Effects of Traffic Accident Reduction "
 Establish simulation technology Develop <u>behavioral models</u> for traffic participants Validation of the simulation technology (Preconditions are tentatively defined) 	Improvement of simulation accuracy ①Enhance the accuracy of the behavioral models ②Establish preconditions

1Enhance the accuracy of the behavioral models

Expand the pedestrian behavior model and establish a new bicycle behavior model

2Establish preconditions

- A. Set dissemination scenarios (*)
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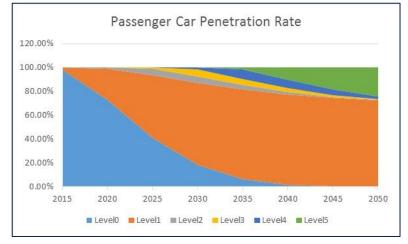
A. Set dissemination scenarios

Dissemination scenarios from another project "Study of the Impact of Automated Driving on Reducing Traffic Accidents and on Others" and vehicle models to be used in this project

11~29 people Commercial Cars Over 30 people Commercial Cars Mini Car Private Cars Sedan 5 Number Private Cars Sedan 3 Number Private Cars Mini Truck Small Truck Truck Haverv Special Vehicle motorcycle bicycle

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Y	Leve	el1	2.5	9%	26.96%	51.9	9%	66.5	5%	71.3	4%	69.8	3%	67.1	3%	65.1	6%	31%	
/	Leve	el2	0.0	0%	1.19%	7.3	1%	6.4	1%	4.7	1%	2.1	4%	0.5	3%	0.1	2%	12%	
Level1 2.59% 26.96% 51.99% 66.55% 71.34% 69.83% 67.13% 65. Level2 0.00% 1.19% 7.31% 6.41% 4.71% 2.14% 0.53% 0. Level3 0.00% 0.00% 1.66% 8.19% 6.70% 4.80% 1.87% 0. Level4 0.00% 0.00% 0.00% 2.10% 10.23% 8.44% 6.09% 2.											0.4		1270						
	Leve	el4	0.0	0%	0.00%	0.0	0%	2.1	0%	10.2	3%	8.4	4%	6.0	9%	2.4	1%		
	Leve	el5	0.0	0%	0.00%	0.0	0%	0.0	0%	2.2	0%	13.6	8%	24.1	2%	31.8	2%		

Dissemination scenarios



Note: Prepared using data provided by the "Study of the Impact of Automated Driving on Reducing Traffic Accidents and on Others ". These figures are provisional and are currently undergoing revision.

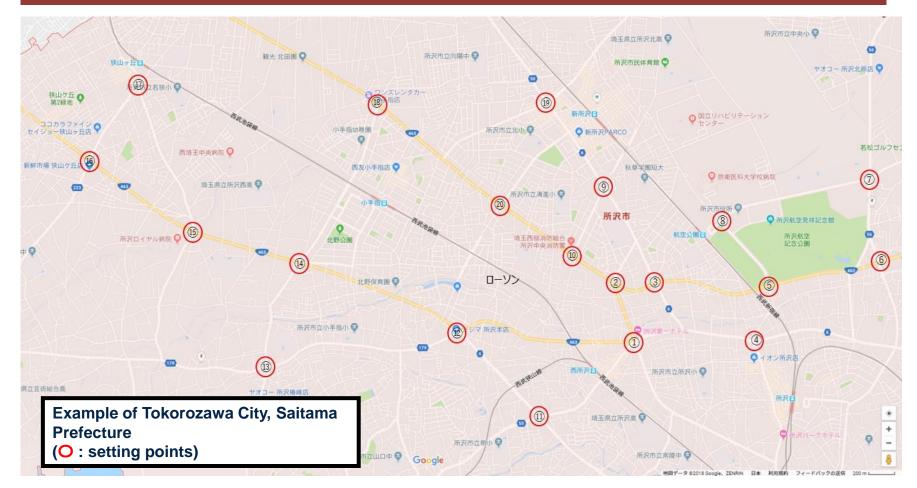
■ Vehicle	Commercial Cars:11~	Commercial Cars:11~29 people Private Cars:Sedan 3 Number					s: Mini C	ar	Heavy Truc	cks		Motorcycle			Special Vehicle					
models	length [m] width [m]	2.065	length width	[m] [m]	value 4.495 1.745	length width	[m] [m]	value 3.650 1.665	length width	[m] [m]	value 5.280 2.080	length width	[m] [m]	value 1.990 0.710	length width	[m] [m]	value 4.910 1.800			
	Commercial Cars:Ove	er 30 people	weight Private Cars	s:Sedan s		weight Small Truck	s	910	weight Mini Trucks	6	2,770	weight Bicycle	- 01	167	weight	[kg]	1,690			
			length width		value 4.910 1.800	length width	Unit [m] [m]	value 4.690 1.695	length width	Unit [m] [m]	value 1.475 2.065	length width	[m]	value 1.850 0.580						
9 3 P		13,180		[kg]	1,690	weight	[kg]	2,000	weight	[kg]	350	weight		20						

B. Set signal indication and traffic regulation information (1/2)

For more accurate simulation,

set signal indication information and traffic regulation information on the map

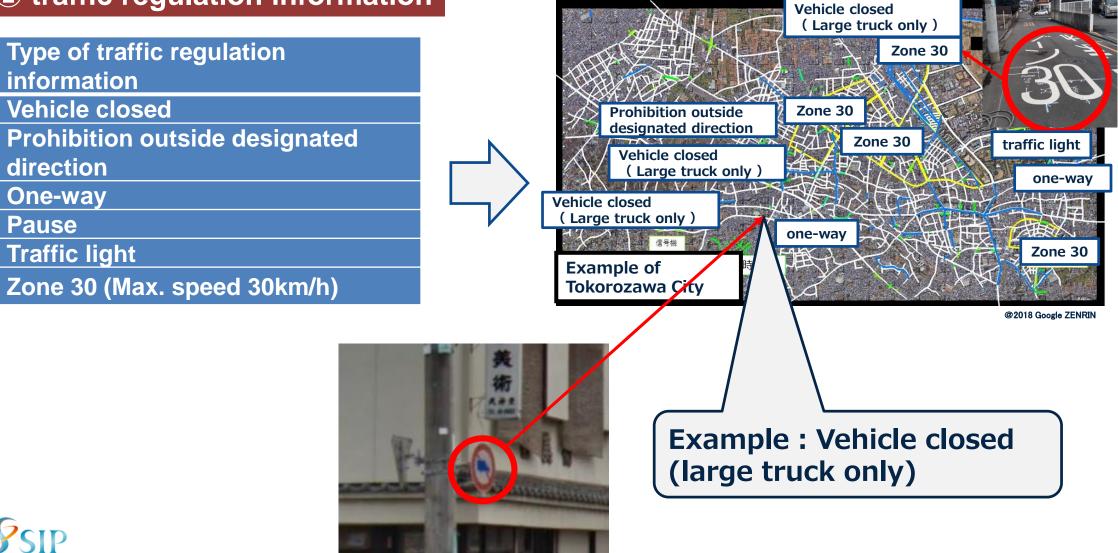
①Signal indication information (include pedestrian signals)



B. Set signal indication and traffic regulation information (2/2)



Pause

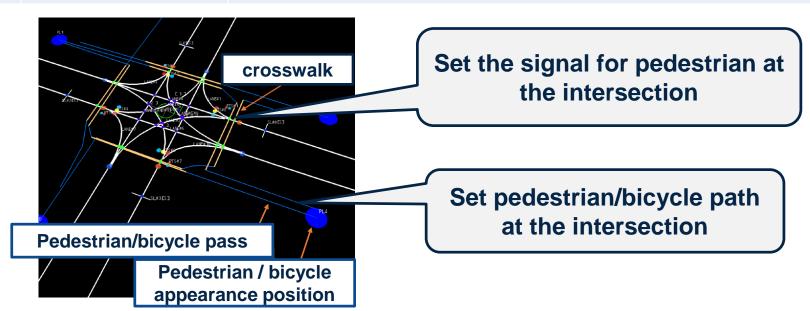


C. Pedestrian and bicycle models and traffic settings (1/3)

Expand the types of pedestrian accidents and establish a new bicycle behavior model to reproduce major bicycle accidents

[Types of accidents reproduced in the simulation of this project]

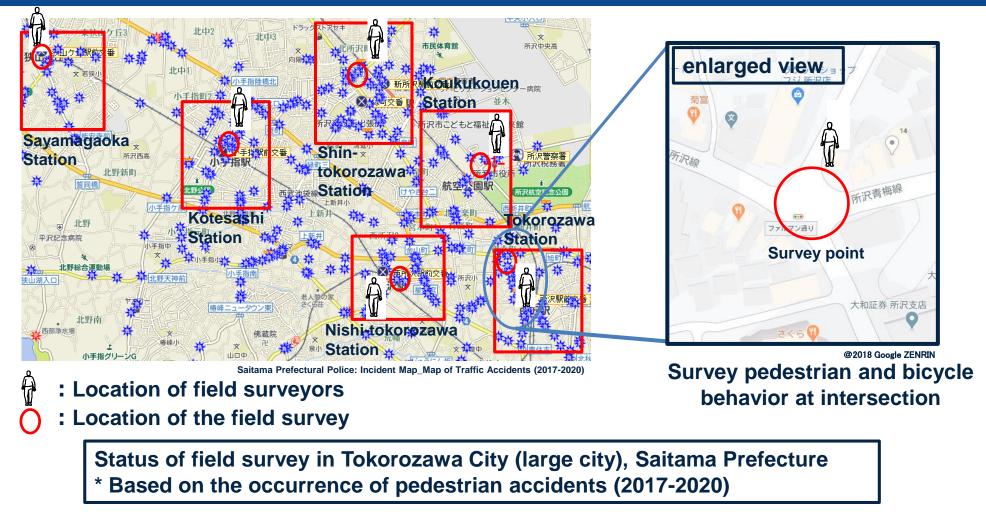
Traffic participants	SIP Phase 1	SIP Phase 2 (this project)
Pedestrian	Single road crossing only	Single road crossing + Crossing signal intersection (only second party)
Bicycle	-	Head-on, Left turn involved, and right straight accidents(only second party)



SIP

C. Pedestrian and bicycle models and traffic settings (2/3)

Traffic volume survey was conducted in each model area, mainly at locations where many accidents occur, and the traffic volume of pedestrians and cyclists was set on the map



C. Pedestrian and bicycle models and traffic settings (3/3)

The volume of pedestrian and bicycle traffic at each survey location was surveyed



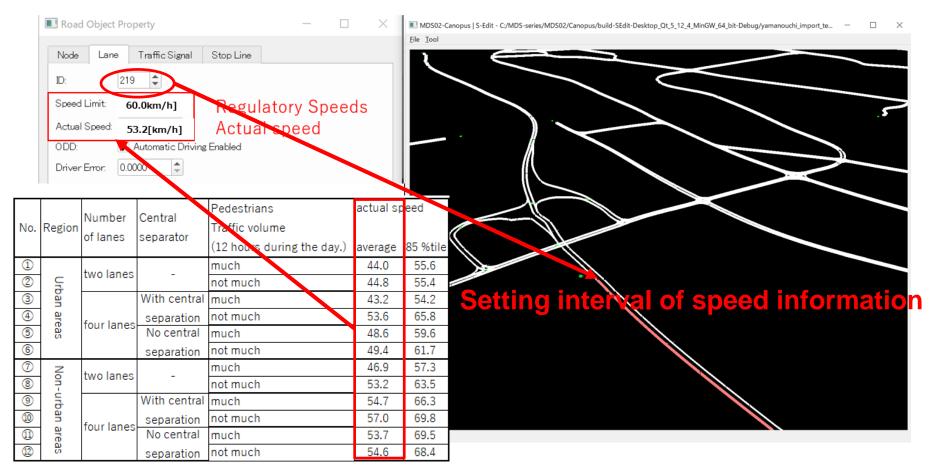
Pedestrian totals										Bicycle total			S	itandard deviat	ndard deviation								
Child	Child Adult Aged total		Child Adult A					Aged		total			Bicycle				Bicycle	Į.					
blue/blinking	red	blue/blinking	red	blue/blinking	red	blue/blinking	red		blue/blinking	red	blue/blinking	red	blue/blinking	red	blue/blinking	red		blue/blinking	red			blue/blinking	red
0	0	51	1	25	0	76	1	Α	0	0	1.186	0.152	0.789	0	0.960	0.089	Α	28	2		Α	0.678	0.089
0	0	89	1	21	0	110	1	В	0	0	1.789	0.152	0.932	0	1.475	0.089	В	27	1		В	0.811	0.089
0	0	154	0	40	0	194	0	С	0	0	2.146	0	0.898	0	2.053	0.089	С	81	2		С	1.163	0
0	0	75	1	22	0	97	1	D	0	0	1.145	0.152	0.545	0	1.048	0.152	D	44	0		D	0.872	0.089
0	0	50	0	19	0	69	0	Е	0	0	1.029	0	0.586	0	0.841	0	E	64	0		Е	1.349	0
0	0	281	0	40	0	321	0	F	0	0	4.003	0	0.872	0	3.785	0	F	102	0		F	1.620	0
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C D E

p Example of Survey Implementation and results in Tokorozawa City, Saitama Prefecture

D. Set speed information

Set the regulatory speed (designated speed or legal speed) and actual speed on the map data

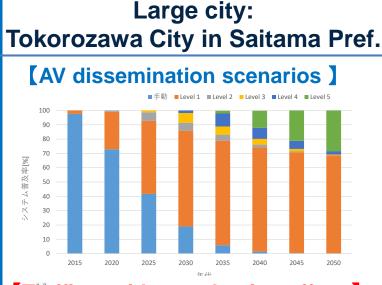


Designated speed and legal speed are set based on the actual designated speed and legal speed in each model area. The actual speed was set with reference to the "Research and Study Report on the Determination of Regulatory Speeds in Fiscal 2008".

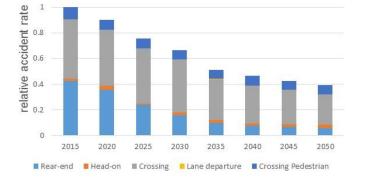
Estimation of traffic accident reduction effect (tentative)

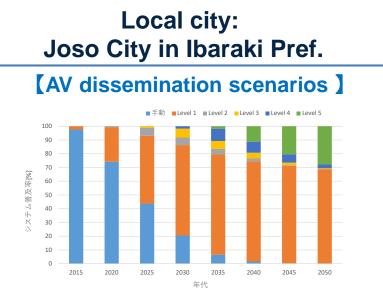


Performed simulations for each model area and estimated the effect of traffic accident reduction (Number of accidents)

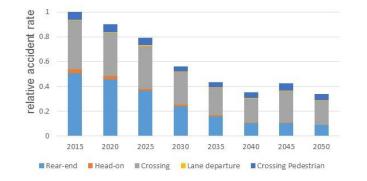


[Traffic accident reduction effect]

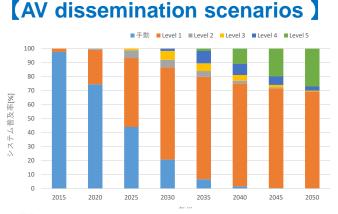




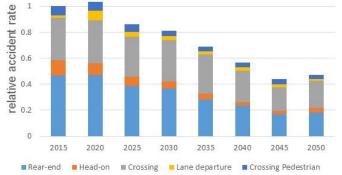
[Traffic accident reduction effect]



Depopulated area: Yamanouchi Town in Nagano Pref.



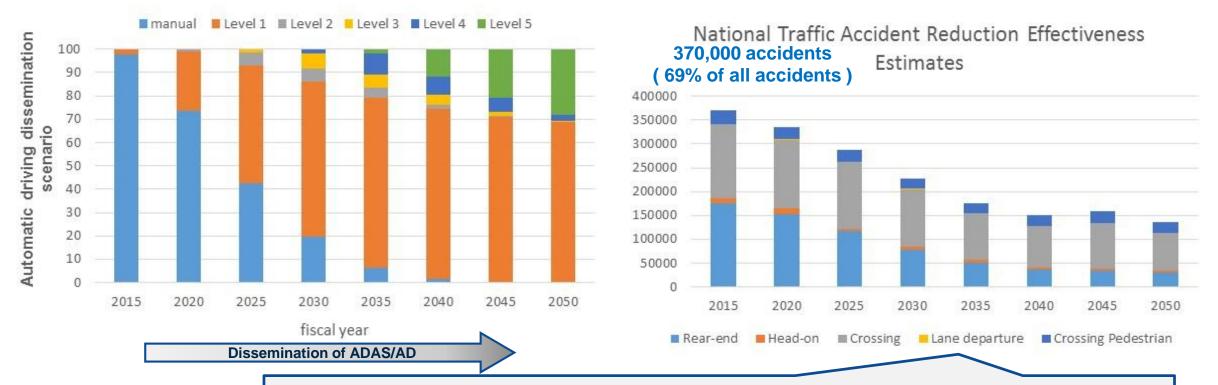
Traffic accident reduction effect]



Estimation of traffic accident reduction effect (tentative)

Based on the reduction effect in each model area, Estimated nationwide traffic accident reductions by using national traffic accident statistics data

[AV dissemination scenarios (National average)]



Confirmed the reduction effect of dissemination, but less reduction in crossing pedestrian and crossing. This is due to the low dissmination of Level 3 and above, and the fact that automated driving system model implemented in this simulation assumes only autonomous sensors and is unable to respond to sudden jumps from out of sight.

[Nationwide traffic accident reduction effect]

Summary



Based on the simulation of traffic accident reduction effects developed in SIP Phase 1, the following data were incorporated to improve the accuracy.

A. Dissemination scenarios
B. Signal indication and traffic regulation information
C. Pedestrian and bicycle models and traffic
D. Speed information

In this project, a tentative accident reduction effect was estimated using a tentative dissemination scenarios provided by another project "Study of the Impact of Automated Driving on Reducing Traffic Accidents and on Others".

The effect of accident reduction will be calculated in the final dissemination scenarios towards the end of the fiscal year.

Japan Automobile Research Institute