

# Status of Connected and Automated Vehicle development in SIP-adus

17 Nov. 2016

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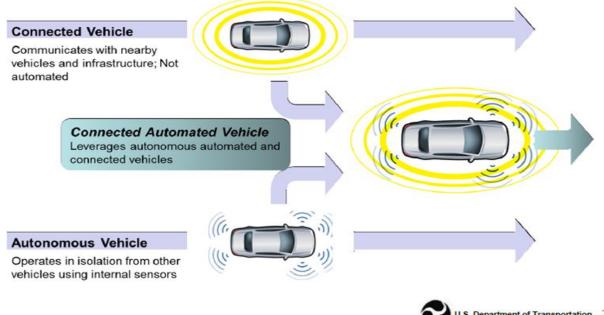
International Cooperation WG, SIP-adus Mazda Motor Corporation

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#### 1. How should we address the automated vehicle with connectivity?

The autonomous vehicle and the connected vehicle should be integrated into ultimate automated vehicle





Having the common USE CASE should be starting line

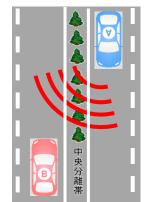
#### 2. Common use case for Connected and Automated by JAMA

#### JAMA defined 4 typical USE CASE

Traffic information from road Realize smooth automated driving by using the safety related information from the road which couldn't be gotten by vehicle sensor -Traffic control info -Traffic jam -Vehicle speed /position

#### Detect and distribute the information

A Send the information B automated vehicle



- 1. Detect hazardous information on the road by vehicle sensor and distribute the information
- 2. Receive the information from other vehicle and redistribute to on coming automated vehicle



#### 2. Common use case for Connected and Automated by JAMA

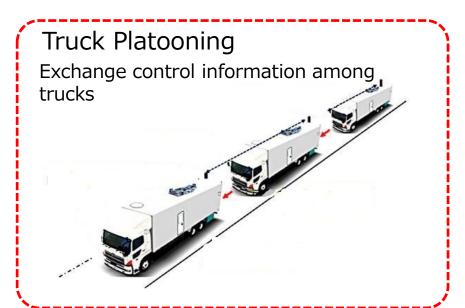
#### Merging/ Lane Change

A Merging vehicle B Following vehicle



①Merging or Lane change request from merging vehicle

- ②Following vehicle respond and make gap
- ③A detect the safe gap and start merging
- 4) Dane safe and smooth merging and lane change





Merging on highway junction is one of the most critical scenario to evaluate communication protocol capability

#### 3. Use of common use case

MIC (Ministry of Internal Affairs and Communications)
Study policy of radio-communication



JAMA (Japan Automotive Manufacturing Association)
Establishing use case for



**ARIB** 

NILIM (National institute for Land and Infrastructure Management)
Study V2I application



Common USE CASE

automated driving

SIP adus (Cabinet Office)

Study communication performance by proving test



ITS Forum (ARIB)

Study radio-communication protocol and standardization

Studying radio-communication application by using common use case.

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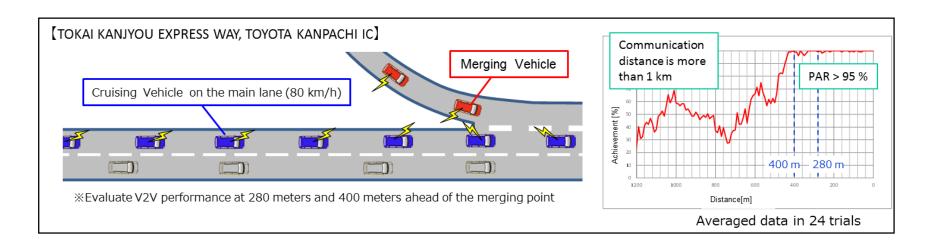
SIP is studying Connected Vehicle applications for automated driving

- 1) V2V Application for Merging scenario based on the use case
  - Clarify capability of current communication protocol (760MHz)
  - Study improvement of communication quality
- 2) V2Pedestrian application
  - Development of portable communication equipment
  - Study pedestrian location identification

1) V2V Application for Merging scenario based on the use case



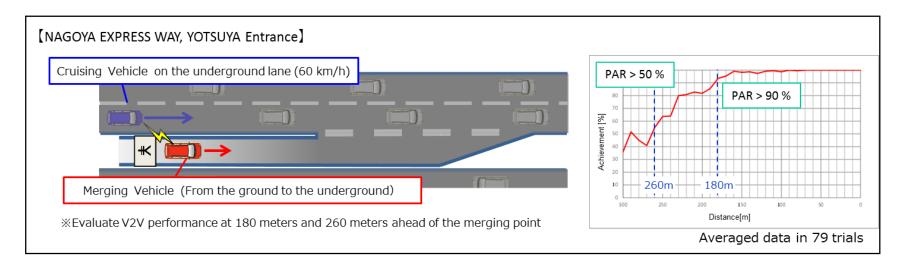
-Current ITS communication protocol in Japan is capable under the open air condition (use of 760MHz)



1) V2V Application for Merging scenario based on use case



-Communication performance is not enough under the isolated condition between merged road and main lane. (e.g. tunnel)



#### 1) V2V Application for Merging scenario



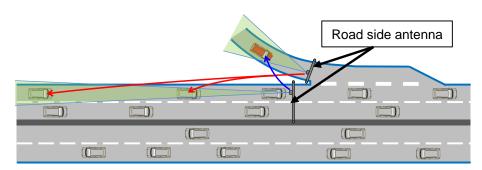
## -Study the possibility of V2I application under difficult situation of communication

#### V2V application

- -Identify the vehicles location for mutual communication
- -Messages for mutual communication

#### **V2I** application

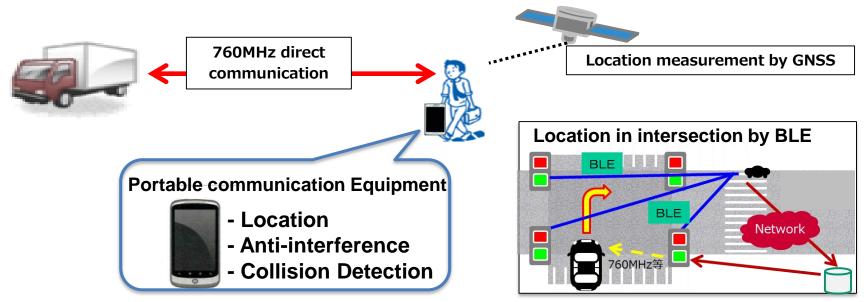
-Required messages to merging vehicle and vehicles in main lane



#### 2) V2Pedestrian application



- -Develop portable equipment for the pedestrian collision warning
- -Pedestrian location measurement performance in urban area
- -Communication performance in crowded condition



### 5. Summary

1. Common use case is the starting line to consider connected and automated vehicle.

2. SIP is studying required performance of connectivity for V2V and V2P applications

### Thank you for your attention