

# The use case for Cooperative Driving Automation

Norifumi Ogawa (Mazda Motor Corporation) Task force on V2X communication for Cooperative Driving Automation



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# 1. Background and Purpose of Use Case Development

 Current status and issues toward the realization of Cooperative Driving Automation (CDA)

#### **Current status of ITS wireless communication in Japan**

- ETC / ETC2.0 (DSRC): Toll collection and Expressway information since 2000
- ITS Connect (DSRC): Support for safe driving at general road intersections since 2015

#### **Challenges for realizing CDA**

- Can ITS communication, which has already been put into practical use, be used for CAD?
- What kind of communication method is needed in the era of automated driving?

- TF on V2X communication for CDA has been established in SIP since 2019
- Started researching communication methods for CDA

# 1. Background and Purpose of Use Case Development

#### Activities of TF on V2X Communication for CDA



#### 2. SIP Cooperative Driving Automation Use Case 1st Edition Overview

SIP Cooperative Driving Automation Use Case 1st Edition

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SIP 協調型自動運転ユースケース

#### -2019 年度協調型自動運転通信方式検討 TF 活動報告-

第1版2020年9月3日

SIP 自動運転(システムとサービスの拡張 システム実用化 WG 協調型自動運転通信方式検討 TF

#### 3. Cooperative driving Automation system definition / scope of research

## Cooperative driving automation system definition

CDA system is that enables safer and smoother automated driving control based on the autonomous driving system, by obtaining the information not detected by the in-vehicle sensor, by providing the information possessed by the vehicles, and by communicating mutually by using V2I and V2V.

# Scope of research

- (1) Passenger Car
- (2) Logistics / Mobile service car

#### 4.1 Use case survey

Survey and collection of use cases used in CDA and ADAS projects in Europe, the United States, and Asia (including Japan) (FY2018)

#### 4.2 Concept of SIP use case selection

Considering the effective use of communication resources, we selected use cases for practical use.

- 1) Consider the preconditions for selecting CDA system
  - (1) All traffic participants shall basically comply with the law.
  - (2) Do not include use cases that can be realized by autonomous driving systems
- 2) Conforms to the definition of CDA system
  - (1) by obtaining the information not detected by the in-vehicle sensor
- (2) by providing the information possessed by the vehicles
- SIP (3) by communicating mutually by using V2I and V2V

## Select 25 feasible use cases

(1) obtaining the information not detected by the in-vehicle sensor(14)

- a. Merging and lane change support (2)
- b. Traffic signal information (2)
- c. Look-ahead information: Collision avoidance (4)
- d. Look-ahead information: Trajectory change (5)
- e. Look-ahead information: Emergency vehicle avoidance (1)
- (2) providing the information possessed by the vehicles (4)
   f. Information collection and distribution by infrastructure (4)
- ③ communicating mutually by using V2I and V2V(7)
   a. Merging and lane change support (4)
   g. Formation / following running (2)
   h. Remote control (1)

### **5. SIP use case selection results**

#### 1) by obtaining the information not detected by the in-vehicle sensor a. Merging and lane change support a-1-1. Preliminary acceleration / deceleration merging support

Functio							
	onal ication	a. Merging	and lane change support				
Use case name		a-1-1. Preliminary acceleration / deceleration merging support					
loc	ation	Expresswa	y + general road	Applic	able Car	Passe	enger vehicle
Ove	<b>Dverview</b> Information such as the speed of vehicles traveling at the measurement point on the main line the estimated time of arrival at the confluence is provided from the infrastructure to the mergovehicle to support preliminary acceleration / deceleration at the confluence.						ne infrastructure to the merging
			Use	case image	:		
				infr		on the	ling information on vehicles travelir e main line (sensing information, ated time of arrival at the
		f vehicles tra	of speed and aveling on the				
8	length of	f vehicles tra				conflue	
Points t	length of main line	f vehicles tra	aveling on the			conflue 	ence)
Points to note	commun	f vehicles tra	V2I	data partition/ Information content	messag	je data	Estimated arrival time at the confluence (main line car) Speed (main line car spot

SIF



# 6. Next step



-Society Automotive Engineers of Japan

# 7. Summary

- Started researching communication methods for CDA in SIP
- Completed the development of use cases to be the basis for the next research
- Use cases opened to the public

(SIP homepage: https://www.sip-adus.go.jp/rd/rddata/usecase.pdf)

- Started researching the definition of communication requirements based on use cases and the applicability to existing ITS communication.
- Consider a new communication method if it is not applicable to existing ITS wireless communication
- Provide the proposal of communication methods for CDA and roadmap until
  SIP the end of FY2021

# Thank you