Project Summary

The Cross-ministerial Strategic Innovation Promotion Program (SIP)
Large-scale Field Operational Test for Automated Driving Systems:
- Information security field operational test -

Deloitte Tohmatsu Risk Services Co., Ltd.
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Contents

Aims and purposes of the field operational test

An FOT will be conducted to establish a method for evaluating network-based attacks on vehicles

Objectives for Research and development of the SIP Automated Driving System

1. Reduce the amount of traffic accidents, etc. and, achieving national goals
2. Realize and popularize the automated driving system
3. Develop the system in cooperation with the Tokyo Metropolitan Government, with the 2020 Tokyo Olympic and Paralympic Games as a milestone

From "Cross-ministerial Strategic Innovation Promotion Program (SIP), Automated Driving System Research & Development Plan" (April 1, 2017)

A large-scale field operation test (FOT) for accelerating implementation of the automated driving system

- **Identifying specific problems** in the fields of technology, operations, and systems
- **Promoting international cooperation and coordination**
- **Promoting accurate public understanding and engendering social acceptance** of automated driving systems, etc.

Five sectors of technology	1. Dynamic Maps 2. Human Machine Interface (HMI) **3. Information security** 4. Pedestrian Accidents Reduction 5. Next-generation Urban Transportation

The information security FOT, a part of the large-scale FOT of the Cross-ministerial Strategic Innovation Promotion Program (SIP) Automated Driving System **(below: "the project")**

Purpose of the project

Through **research and analysis of security threats** in the field of automated driving, **the development of security evaluation methods and protocols** for the vehicle and component levels with a view to establishing international standards, and the use of vehicles provided by those participating in the **FOT** to undertake a black box experiment testing resistance to hacking, the project aims to achieve the following:

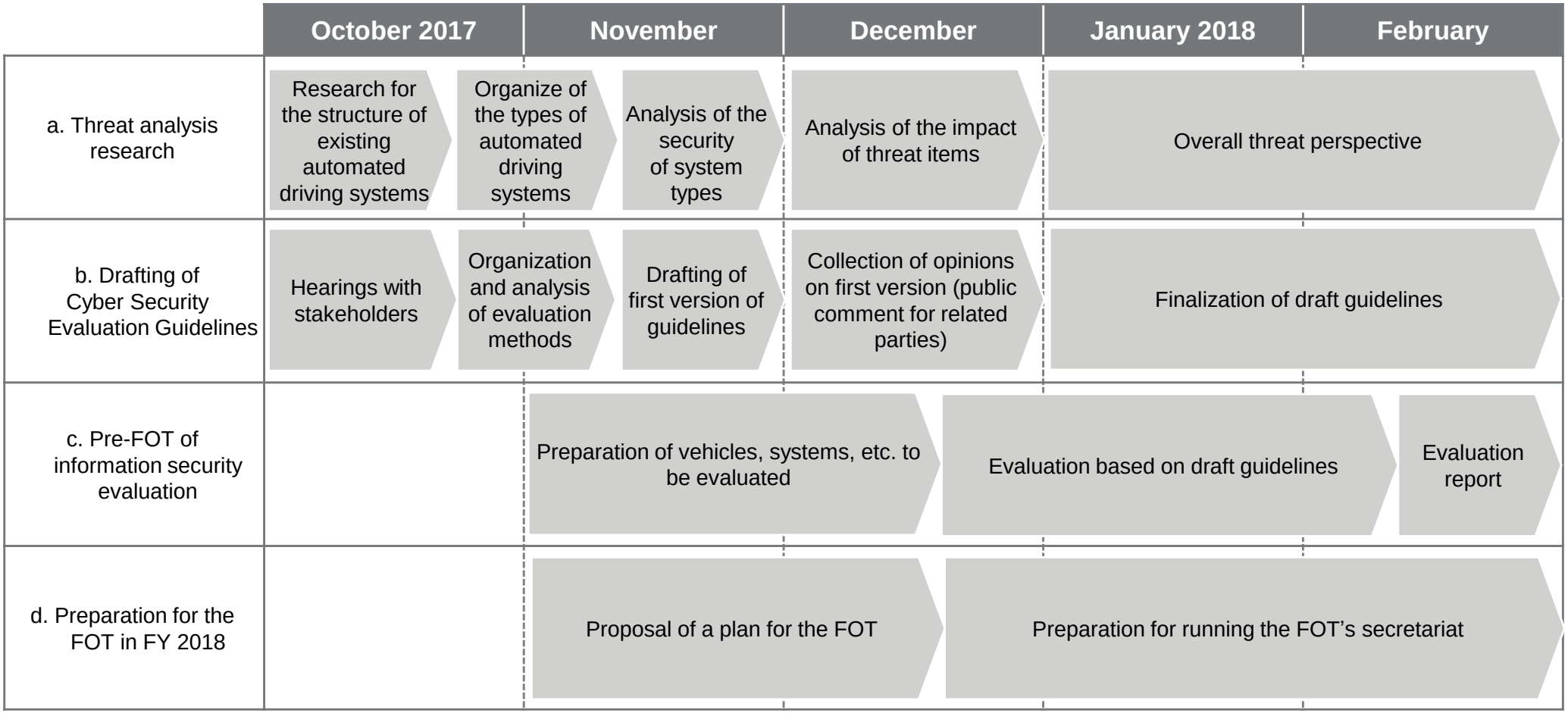
1. **Establish a method for evaluating network-based attacks on vehicles**
2. **Organize the full range of threats, including V2X-related and other external attacks**
3. **Build consensus about autonomous vehicle security**
4. **Develop human resources and accumulate knowhow related to autonomous vehicle security in Japan**

From "Application guidelines related to the 'information security FOT' part of the 'large-scale FOT of the Cross-ministerial Strategic Innovation Promotion Program (SIP) Automated Driving System'" (July 2017)

(Relation of each task to the aims of the project)

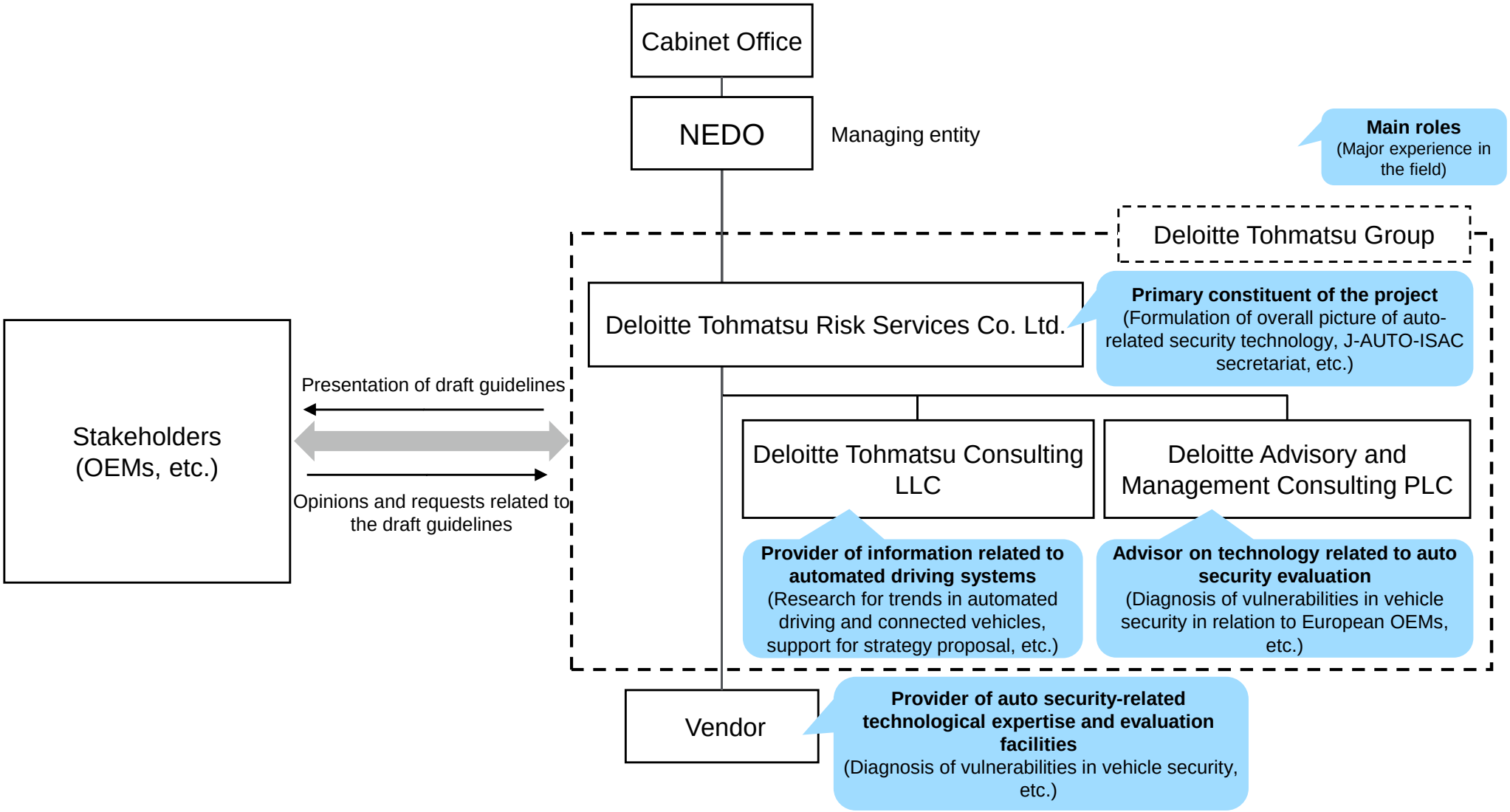
Overall schedule

XXX



Implementation structure

The project has been conducted in cooperation with the Deloitte Tohmatsu Group's consultant teams including an overseas member firm with technological expertise and proven track records



Threat analysis research

Approaching the threat analysis research

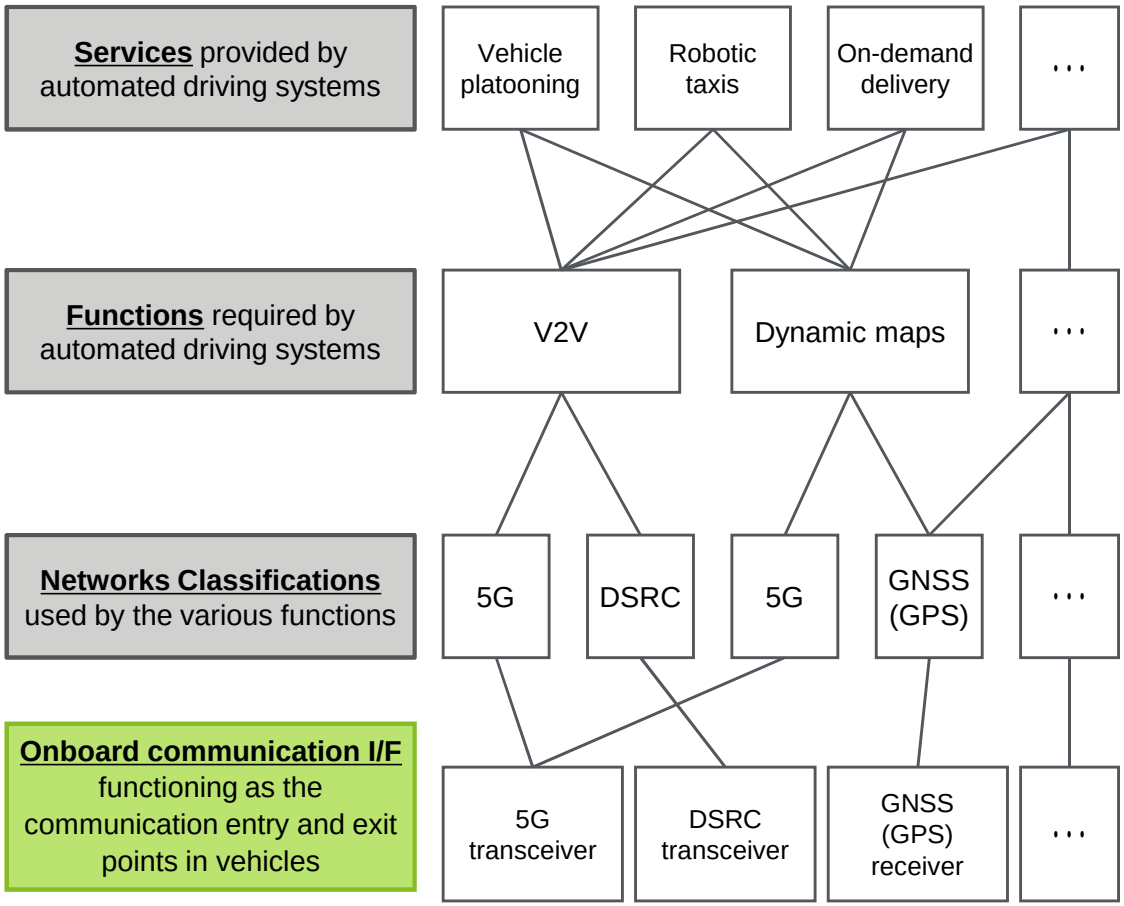
In order to identify the overall perspective of cyber threats to automated driving systems, we will conduct a research for the components of such systems and analyze expected threats to them

	Modeling and researching for components of automated driving systems	Threat analysis
Steps to be implemented	• Modeling of automated driving systems • Research for services and functions constituting automated driving systems • Organize network types and onboard communication I/F	• Development of scenarios for wireless network-based external attacks on autonomous vehicles • Evaluation of threat levels • Classification of threats • Organize the overall threat perspective for automated driving systems
Main outcomes	• Results of the service research • Results of the functions research • Results of the Networks Classifications research • Results of the research for onboard communication I/F	• List of threat scenarios • Threat evaluation index • Results of threat evaluation • Overall threat perspective

Model for threat analysis of automated driving systems and research/organize procedures

By modeling automated driving systems, and researching and organizing the components of each of their layers, we can identify the onboard communication I/F that function as entry and exit points in vehicles for wireless communications

Model for threat analysis of automated driving systems and their components



Research/organize procedures

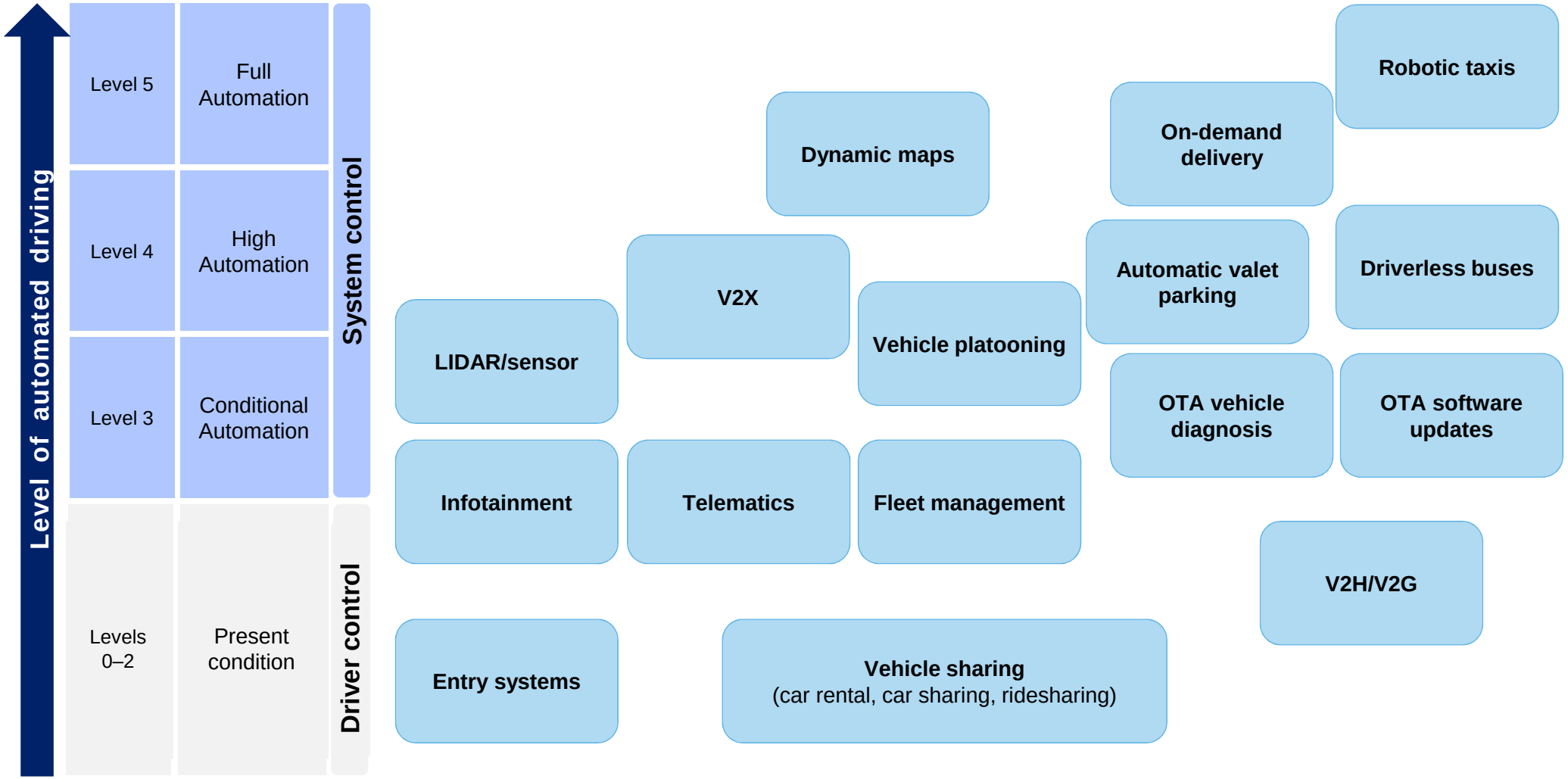
1 Research for auto manufacturers and suppliers' undertakings, FOTs, etc.

2 Listing of the functions that make up each service

3 Since networks used in each functions varies, identifying specific networks required to each function is necessary.

Services provided by automated driving systems (including some functions)

By comprehensively researching and organizing the services provided by automated driving systems, the overall perspective of cyber threats becomes identified



Services and functions are commodified as automated driving systems evolve

Results of the automated driving systems functions research

The functions included in automated driving systems can be summarized as follows

Level of automated driving

System control

Driver control

Getting in/preparing for driving	Driving	Parking	Maintenance
• Destination setting	• Dynamic maps • V2X (communication with nearby devices) ➢ Vehicle-to-pedestrian (V2P) communication ➢ Vehicle-to-infrastructure (V2I) communication ➢ Vehicle-to-vehicle (V2V) communication • Entertainment ➢ Concierge ➢ Internet access ➢ Point of Interest (POI) information, etc. • Storage and transmission of onboard data (travel history, external environment, vehicle status, etc.) • Identification of surroundings • Emergency call • Driver monitoring	• Parking support ➢ Parking assistance ➢ Remote-controlled parking ➢ Automated parking • Parking lot assistance ➢ Acquisition of empty parking space data ➢ Reservation ➢ Payment	• Vehicle dispatch (robotic taxis etc.) • OTA vehicle management ➢ Software and firmware updates ➢ Vehicle diagnosis • V2G (linking with grid) • V2H (linking with home systems) ➢ Charging and electricity supply ➢ Linking with IoT devices in the home • Navigation (data updates)
• Linking with carry-in devices ➢ Connecting with portable devices			
• Entry system ➢ Locking and unlocking doors ➢ Starting the vehicle			

See Appendix B for a structure chart of the above functions

Results of the organize of wireless and communication I/F

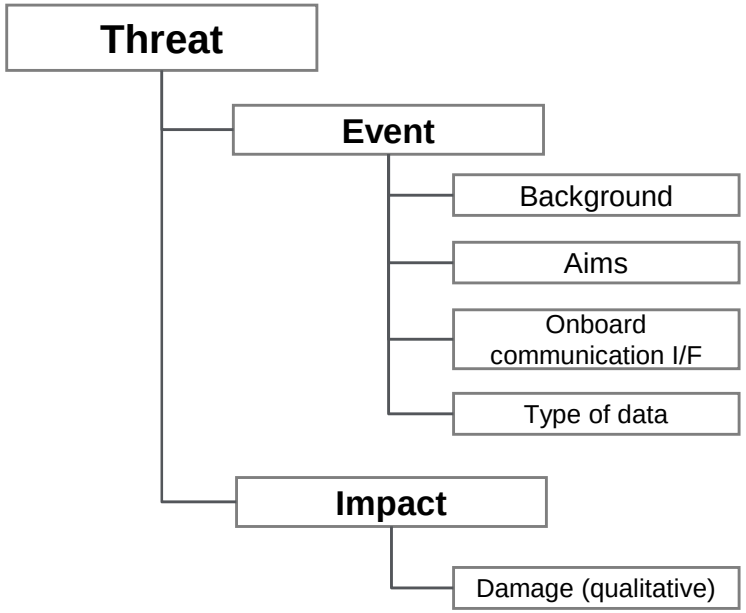
Summary of the types of networks and onboard communication I/F used by automated driving systems

Types of Networks	Networks Classifications	Onboard communication I/F	Point(s) of connection from the vehicle	Examples of information communicated
Public network	5G	5G transceiver	Nearby vehicles, cellphone carriers' base stations, service providers' servers	Cruise control data, dynamic map data, etc.
	3G/4G	3G/4G transceiver	Cellphone carriers' base stations, service providers' servers	Software updates, traffic information, infotainment
Wi-Fi	Wi-Fi	Wi-Fi transceiver	Wi-Fi hotspots, service providers' servers	Software management data, vehicle location data, traffic information, infotainment
V2X communication	Cellular V2X	Cellular V2X transceiver	Nearby vehicles, infrastructure, etc.	Traffic information, cruise control data, etc.
	DSRC	DSRC transceiver device (V2X)	Nearby vehicles, infrastructure, etc.	
Device-to-device communication	Bluetooth (for VCK and portable devices)	Bluetooth transceiver	Smartphones and other portable devices	Identification data used by the entry system, information on linked portable devices, etc.
	Bluetooth (for OBD-II)	OBD-II dongle	Wi-Fi hotspots, service providers' servers	Software management data, diagnostics
	ZigBee	Wireless ZigBee module	Power grid, homes	Vehicle body control data
Remote sensing	Millimeter-wave radar (77/79GHz)	Millimeter-wave radar transceiver	Nearby vehicles, pedestrians, obstacles	Cruise control data
	Quasi-millimeter-wave radar			
	LIDAR	LIDAR transceiver		
	Ultrasonic sensor	Ultrasonic sensor transceiver		
	Biometric sensor	Biometric sensor	Passengers (fingerprints, irises, expressions, etc.)	Biometric data
Satellite transmission	GNSS (GPS)	GNSS (GPS) receiver	GPS satellites	Vehicle location data
Data provision (VICS etc.)	Quasi-microwave	Quasi-microwave terminal	Roadside devices (radio beacons)	Traffic information (congestion, accidents, etc.)
	Infrared	Infrared terminal	Roadside devices (infrared beacons)	
	DSRC	DSRC transceiver device (VICS/ETC)	Roadside devices (radio beacons), nearby vehicles	Traffic information, cruise control data, asset data
Entry system	NFC	NFC reader/writer device	Contactless IC cards, smartphones	Asset data
	RF/LF (RFID)	RF/LF (RFID) reader/writer	Smart keys	Vehicle body control data

Structure of threat scenarios

To make threat scenarios understandable, organized by events and impact

Premises	■ Threat scenarios are developed for each type of Onboard communication I/F ■ Threat scenarios are based on uniform structural rules to prevent variation in interpretations ■ Work is done to develop, evaluate, and organize threat scenarios going forward with following the rules below



On developing threat scenarios

- Clearly define factors such as the attack's background, aims, and type of relevant data
- On the level of the device in question, express what type of security breach (information disclosure, tampering, etc.) has occurred by clarifying the "event" (what has happened) and "impact" (what will happen) in the scenario
- Use as few technical terms as possible, making your scenario understandable for a broad audience
- Reinforce the concreteness of your scenario by telling a qualitative story about the effects that the event could cause

Example of threat scenario Tampering	**[Event]** Authentication data exchanged between a Bluetooth-equipped vehicle and a VCK (smartphone) is encrypted with ransomware **[Impact]** The vehicle becomes unusable, the attackers demand money

Developing STRIDE-based threat scenarios for each type of Onboard communication I/F

Develop STRIDE-based threat scenarios based on the “event” and “impact” structure in order to prevent issues such as variation in and insufficiency of threats

Classification of threats	Examples of threat scenarios
Spoofing	Event: By interfering with communications between the vehicle and GNSS (GPS) and transmitting a disguised signal, the attacker poses as a GPS satellite Impact: Location data cannot be acquired, making it impossible to set destinations and routes for the vehicle
Tampering	Event: By remotely tampering the software update data on communications, the attacker causes abnormalities in cruise control-related software Impact: As the attacker intended, abnormal limitations on vehicle control occur while driving, impacting driving safety
Repudiation	Event: Communication between an onboard ETC device and the ETC system at a tollgate is repudiated, resulting in the denial of fee payment Impact: Economic loss occurs as a result of this act of fraud
Information disclosure	Event: An attacker providing a fake hotspot or fraudulent free Wi-Fi access point approaches the target vehicle and, once the vehicle connects to this access point, steals the communication data Impact: The vehicle’s destination, route, user ID, password, and other details are stolen
Denial of service	Event: A large quantity of packets are transmitted to a specific vehicle, bringing telematics services to a standstill Impact: The vehicle’s network communication functions are stopped and no network-based services can be used
Elevation of privilege	Event: The attacker remotely inputs unauthorized codes and commands, seizing administrator rights for a 4G transceiver and using it to access other devices connected to the onboard network Impact: The attacker’s use of devices and functions other than the 4G transceiver result in an intended malfunction of the accident evasion system, impacting driving safety

Evaluating threat scenarios

The level of a threat included in a scenario is evaluated by actualization rate and level of impact

Actualization rate

Analyzed separately from each viewpoint and then evaluated comprehensively, this refers **to how easy it is for an attacker to successfully carry out the threat**, irrespective of the characteristics and structure of the vehicle

Viewpoint		Evaluation method
1	Ease	Ease with which the attack can be carried out
2	Devices/tools	Need for special tools and devices
3	Preparation time	Preparation time required to carry out the attack (concealment etc.)
4	Number of attackers	Number of people required to carry out the attack
5	Vehicle status	Status of the vehicle being attacked (driving or parked)

Level of impact

Comprehensive evaluation of the **safety impacts and consequences** to the attacked vehicle and its surrounding environment

Viewpoint		Evaluation method
1	Level of lost functions	Impact on driving (driving, turning, stopping)
2	Level of damage	Safety impact on passengers
3	Scope of damage	Impact on the infrastructure, other vehicles, and pedestrians near the attacked vehicle

On evaluation

Evaluate the threat level of each threat by assigning a number to both the likelihood of actualization and the level of impact the actualized threat would have

Threat level

Level of impact \ Actualization rate	1	2	3
3	4	5	6
2	3	4	5
1	2	3	4

Overall threat perspective

Threat tendencies calculated by actualization rate and level of impact on driving safety

Scores in the chart are averages of the threat level for each communication I/F by STRIDE classification. See slide 14 for how to calculate threat level.

— ; No applicable scenario

Types of Networks	Onboard communication I/F	Classification of threats					
		Spoofing	Tampering	Repudiation	Information disclosure	Denial of service	Elevation of privilege
Public network	5G transceiver	5	6	4	4	5	5
	3G/4G transceiver*	5	6	4	3	4	3
Wi-Fi	Wi-Fi transceiver	5	4.5	—	4	4	5
V2X communication	Cellular V2X transceiver	5	5	3	4	5	4
	DSR transceiver (V2X)	5	5	5	3	5	3
Device-to-device communication	Bluetooth transceiver (for VCKs and other portable devices)	4	3	4	4	4	3
	Bluetooth transceiver (for OBD-II)	6	4.5	—	4	6	5
Satellite transmission	GNSS (GPS) receiver	4	4	—	—	4	—
Data provision (VICS etc.)	Quasi-microwave terminal	3.5	3	—	—	3	—
	Infrared terminal	3	4	—	—	3	—
	DSRC transceiver (VICS/ETC)	3	2	2	3	3	—
Entry system	NFC reader/writer device	3	4	4	4	4	4
	RF/LF (RFID) reader/writer	4	3	—	3	3.5	—

*As scenarios were developed for both 3G and 4G, the one with the higher threat level score is displayed here

The analysis shows that threat levels tend to be high for onboard communication I/F which communicate information necessary for driving safety

How to proceed going forward

Applying the results of the threat analysis to the security guidelines

Threat analysis results	Cyberattacks on the following kinds of onboard communication I/F have a significant impact on automated driving systems

Onboard communication I/F with high threat levels		Part of security guidelines to be evaluated
Public networks	5G transceivers	➢ Cyber Security Evaluation Guidelines - DRAFT - (Practical Manual - IP Network) ➢ Cyber Security Evaluation Guidelines - DRAFT - (Practical Manual - Wi-Fi) ➢ Cyber Security Evaluation Guidelines - DRAFT - (Practical Manual - Bluetooth)
	3G/4G transceivers	
Wi-Fi	Wi-Fi transceivers	
Device-to-device communication	Bluetooth transceivers	
V2X communication	Cellular V2X transceivers	V2X communication is at the experimental stage with a view to practical realization in the future. As its specifications have yet to be standardized (as of January 2018), it will need to be revisited later
	DSRC transceiver	

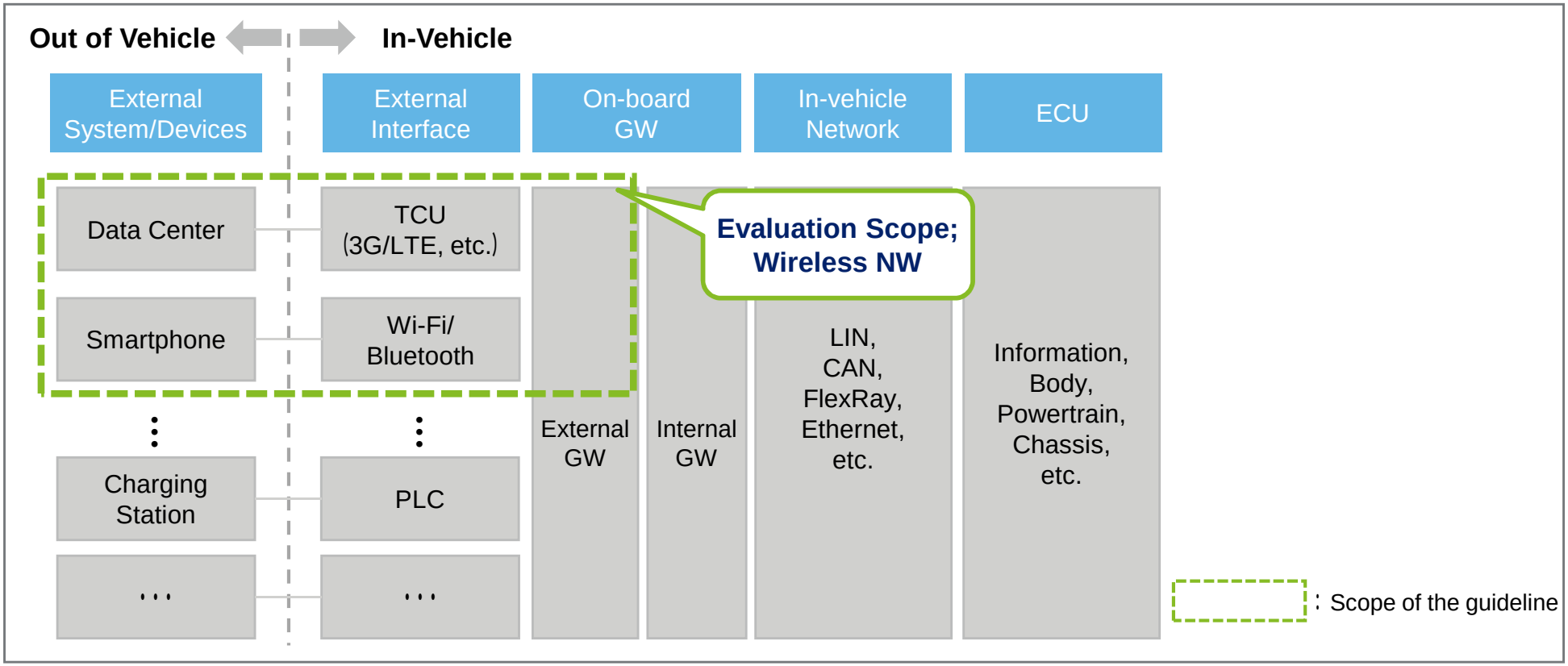
Security guidelines for onboard communication I/F used for commodified networks with high threat level should preferentially be developed

Drafting of Cyber Security Evaluation Guidelines

Scope of Cyber Security Evaluation Guidelines - DRAFT -

Evaluation Scope: Wireless Network Path

Scope	■ Cyber attacks on vehicles through wireless network from external system/devices to external GW ■ Drafted Guidelines as “Methodology” to cover the testing framework and “Practical Manual” to cover specific evaluation approaches for each communication protocol



Characteristics of Cyber Security Evaluation Guidelines - DRAFT -

Seven Advantages

- Providing testing methods applicable to not only vehicle integration testing and commercially available vehicles but also system design phase
- Clarifying use cases and penetration test conductors during V-model process

- Providing test approach for effective use of test resources (e.g. time, manpower, cost)

- Ensuring reproducibility and objectivity by eliminating individual judgement in evaluation procedure

- Applied methodologies to penetration test project for European OEMs
- Including knowhow derived from past penetration test project
- Ensuring effectiveness with cooperation with stakeholders through development process

- Ensuring sufficiency with considering known vulnerabilities to both automotive and IT system
- Possible to add OEM specific evaluation items using the methodology provided in the Guideline

- Introducing detailed description of commands and execution results in Practical Manuals
- Understandable description for penetration testers

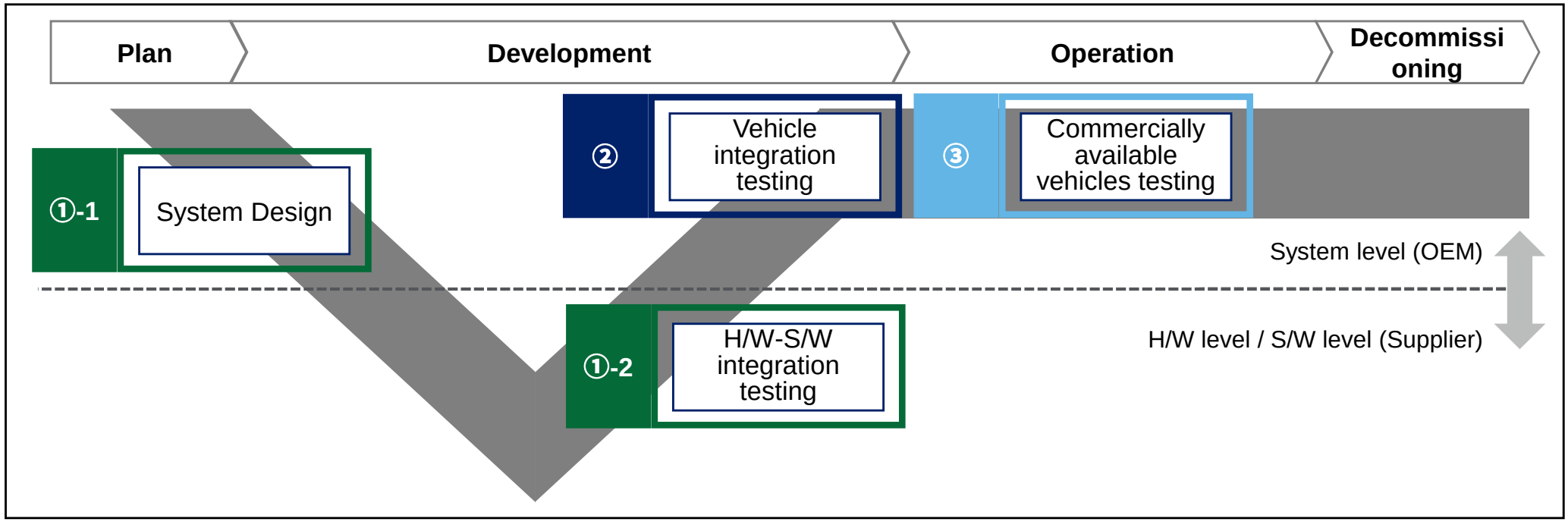
- Easy to expand the scope to in-vehicle network level by adding new practical manuals

Key Points of Drafting Evaluation Guideline (1/7)

Usable Guideline through Development Process

1 Usability

- Method applicable to not only vehicle integration testing and sold vehicle testing but also system design phase
- Clarifying use cases and penetration teste conductors during V-model process



①-1	Available to make penetration test plans in earlier stage using this guideline
①-2	Possible to execute penetration test in advance at H/W-S/W integration testing phase
②	Guideline applicable to vehicle integration testing phase before product released in to market
③	Guideline applicable to sold vehicle already in market

Key Points of Drafting Evaluation Guideline (2/7)

Efficient and Effective Resource Allocation

2	Efficiency

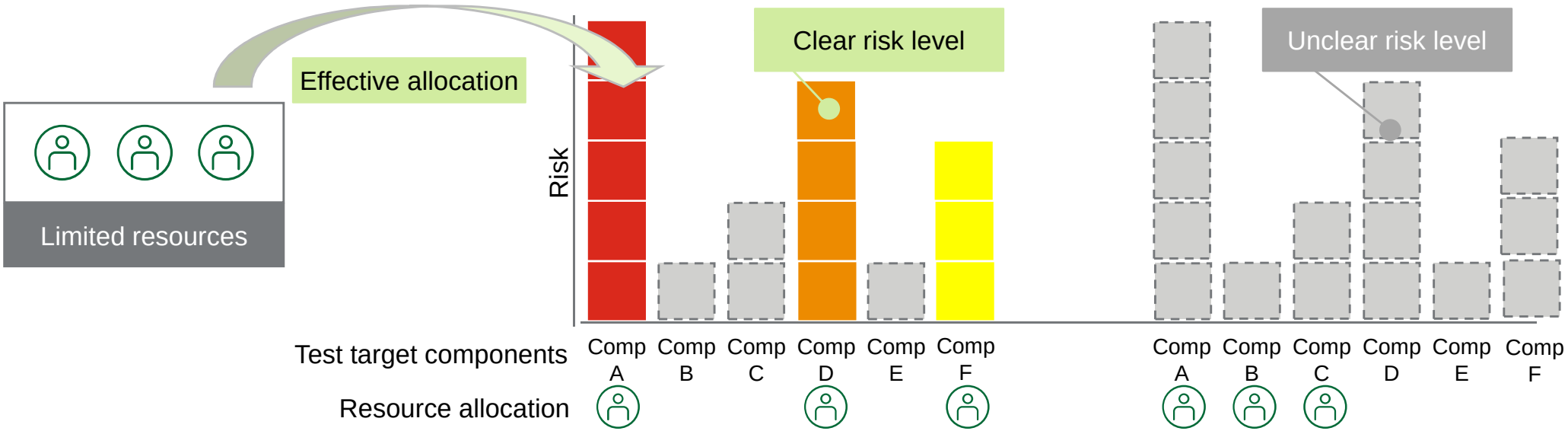
- Providing test approach for effective use of test resources (e.g. time, manpower, cost)
- Risk analysis with attacker view enables efficient penetration test by focusing on high risk level component

Penetration test focusing on high risk level component

Cyber Security Evaluation Guideline

Risk analysis makes it possible to allocate resources effectively and conduct efficient testing

Unable to allocate proper resources if component risk level were not evaluated



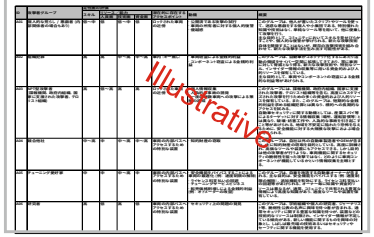
Key Points of Drafting Evaluation Guideline (3/7)

Templates for Risk Analysis and Penetration Test

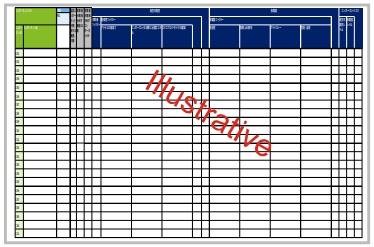
3 Reproducibility

- Ensuring reproducibility and objectivity with using prepared templates
- Eliminating individual judgement in the evaluation procedure to maintain objectivity

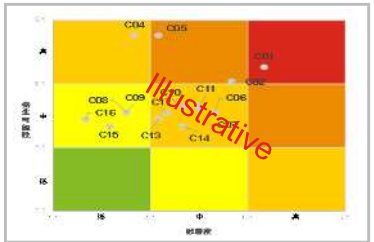
Templates for risk analysis



Attacker profiles

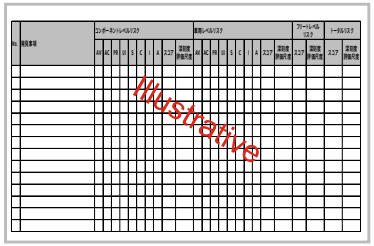


Risk analysis

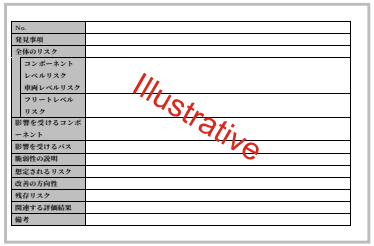


Risk heat map

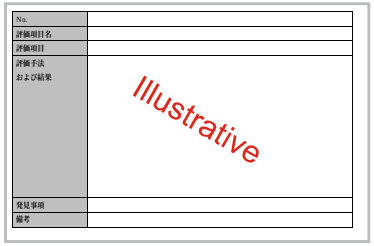
Templates for findings and evaluation result



Risk evaluation for identified vulnerabilities



Findings from evaluation



Evaluation results

Key Points of Drafting Evaluation Guideline (4/7)

Best Practices and Public Comments

4	Effectiveness	■ Referring the guidelines accepted as practical standard in IT system field ■ Previously applied method to penetration test projects for EU OEMs ■ Including know-how derived from past penetration test projects. ■ Ensuring effectiveness incorporating public comments from stakeholders

Best practices of IT system

Considering practical guidelines and methodologies in IT system area

Guideline	NIST Technical Guide to Information Security Testing and Assessment
Guideline	PCI Security Standards Council Penetration Testing Guidance
Guideline	OWASP Risk Rating Methodology

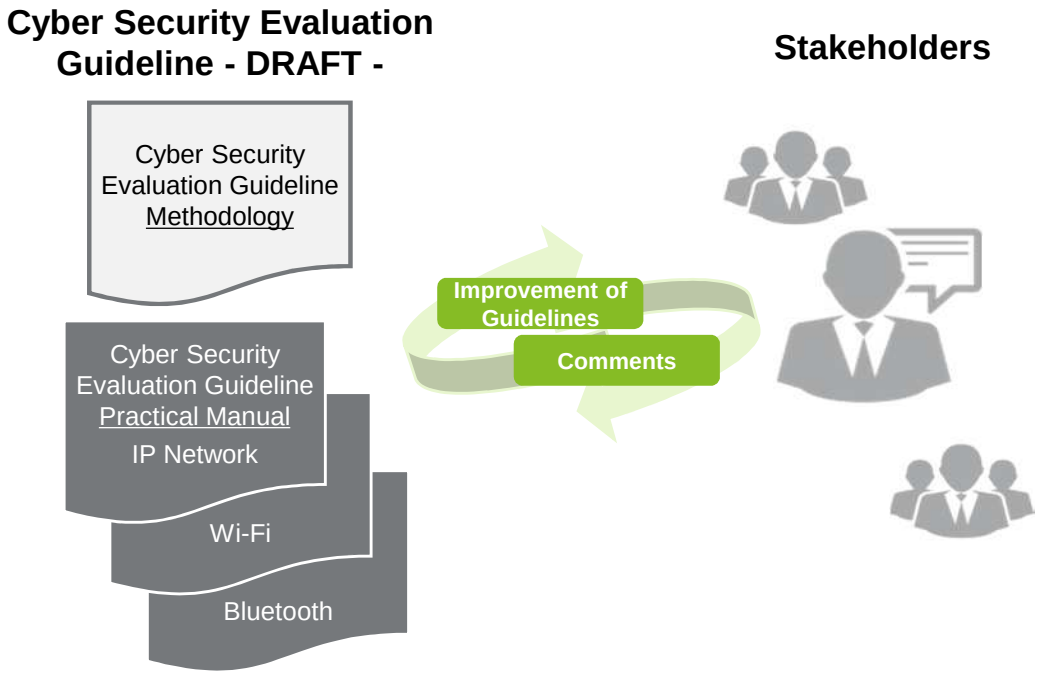
Proven methodology for Automotive

Applied methodologies to EU OEMs and verified through penetration projects

Methodology	Deloitte Automotive Cyber Security Pentest Methodology

Public comments from stakeholders

Ensuring effectiveness by public comment from several stakeholders



Key Points of Drafting Evaluation Guideline (5/7)

General Evaluation Items considering sufficient vulnerabilities

5	Sufficiency	■ Evaluation items for vulnerabilities known in automobile and vulnerabilities known in IT systems applicable to automobile are listed in Guideline (Methodology) ■ Possible to add specific evaluation items using the methodology provided in the Guideline(Methodology)

Vulnerability Category		Vulnerabilities to be considered	Points of Developing Evaluation Items
Known in Automobile		■ Example of Incidents Cases ➢ Vulnerability in In-Vehicle Infotainment System ➢ Vulnerability in Connected Services ➢ Vulnerability in Wireless LAN ➢ Vulnerability in Mobile Application, etc.	■ Referring to security research reports, in addition to past incident and attacks on vehicles
Unknown in Automobile	Known in IT System	■ Applicable to automobile among known vulnerabilities in IT system ➢ Vulnerability in Connected Server ➢ Vulnerability in Web Application ➢ Vulnerability in Mobile Application, etc.	■ Organized known vulnerabilities based on CWE ■ Referring to SANS Top 25 and OWASP TOP to study vulnerabilities applicable to automobile ■ Referring to CAPEC, etc. to develop evaluation items
	Others	Out of scope ※ Appropriate update is needed based on newly disclosed vulnerability of automotive and IT system area	

: Vulnerabilities considered in the general evaluation item list in the guideline (Methodology) Annex

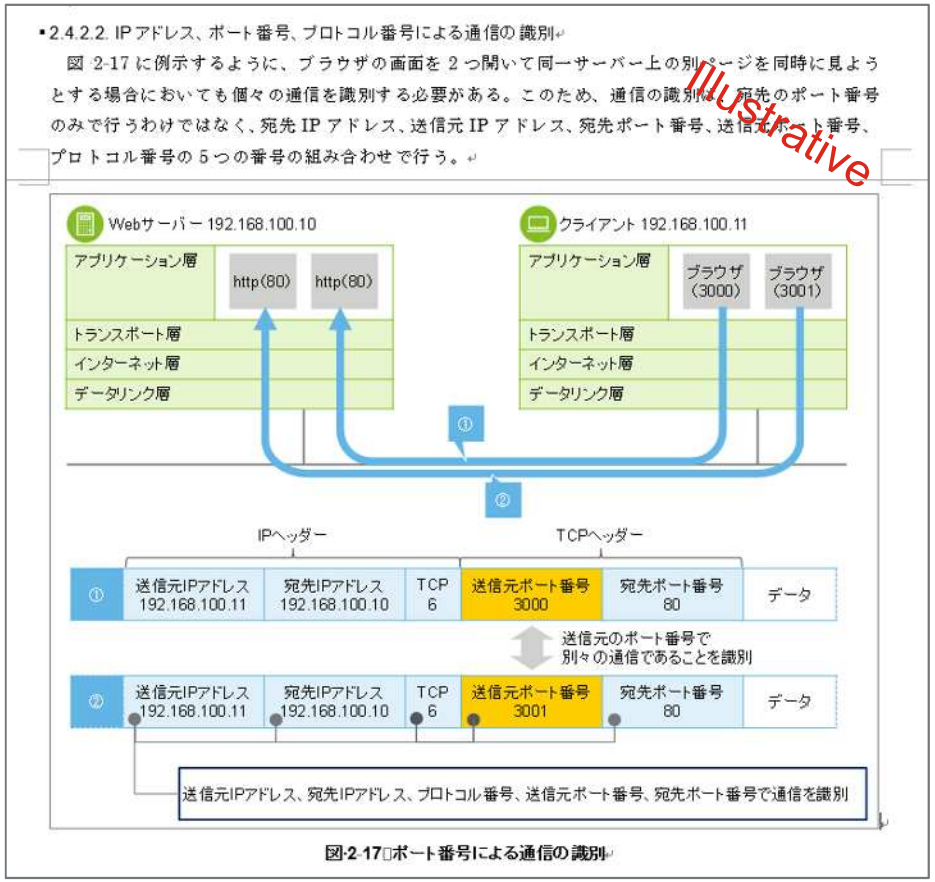
Key Points of Drafting Evaluation Guideline (6/7)

Practical Description and Example

6 Specific

- Introducing detail description of commands and execution results in the Guideline (Practical Manuals)
- Understandable description for penetration testers

■ Graphical description



■ Detail description of commands and execution results

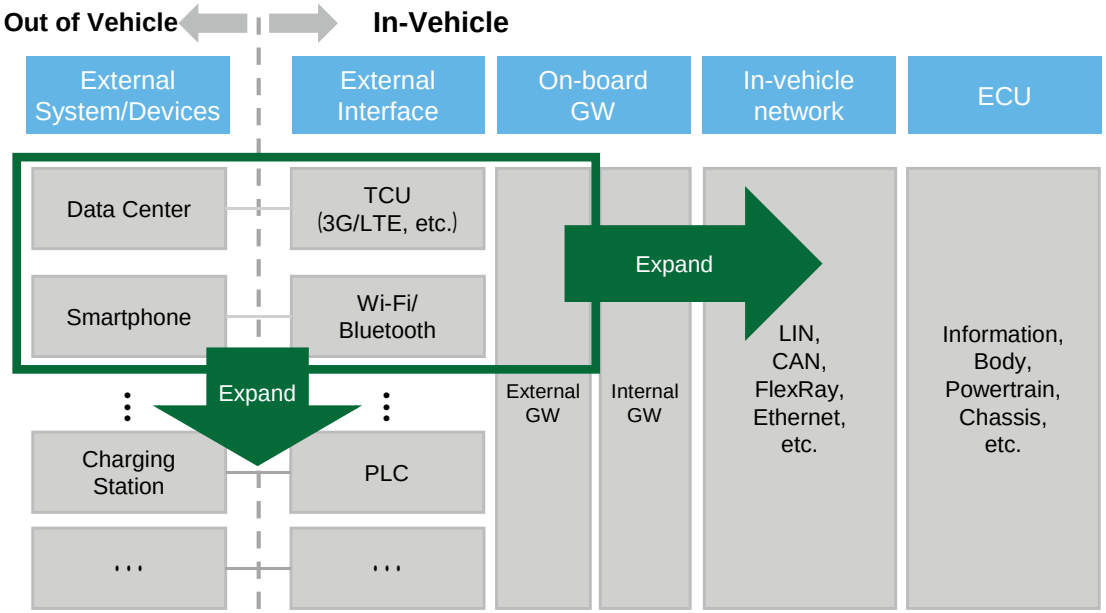
Key Points of Drafting Evaluation Guideline (7/7)

Ensuring Expandability of Guideline

7	Expandability

- Able to expand the testing scope by adding “Practical Manual” of other communication protocol
- Contents in "Methodology" cover the testing approaches and are not dependence on communication protocols

: Scope of the guideline



Expandability of evaluation scope

It is possible to expand the scope by adding practical manual of other protocol

Cyber Security Evaluation Guideline Methodology

Cyber Security Evaluation Guideline
Practical Manual

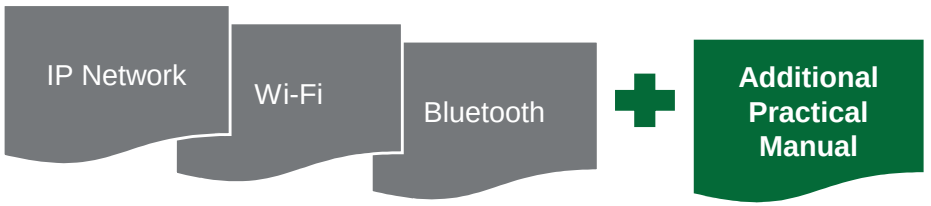


Image of Cyber Security Evaluation Guidelines - DRAFT -

Developed Guidelines of "Methodology" and three "Practical Manual" more than total 500 pages

Cyber Security Evaluation Guidelines- DRAFT -
Methodology

< Outline >

- Threat Perspective
- Evaluation Process
- Evaluation Report
- Appendix1：Threat List
- Appendix2：Evaluation Item List

Bluetooth

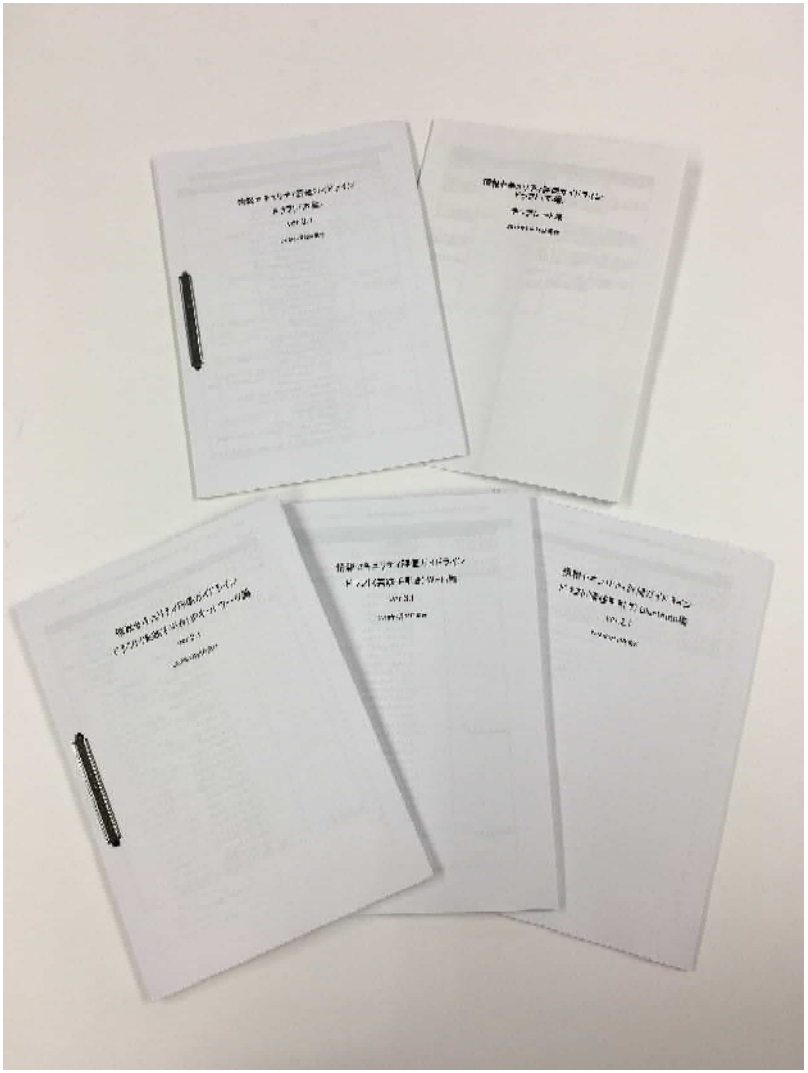
Wi-Fi

IP Network

Cyber Security Evaluation Guidelines- DRAFT -
Practical Manual

< Outline >

- Protocol Overview
- General Attack Methods
- Testing Tools
- General Evaluation Methods



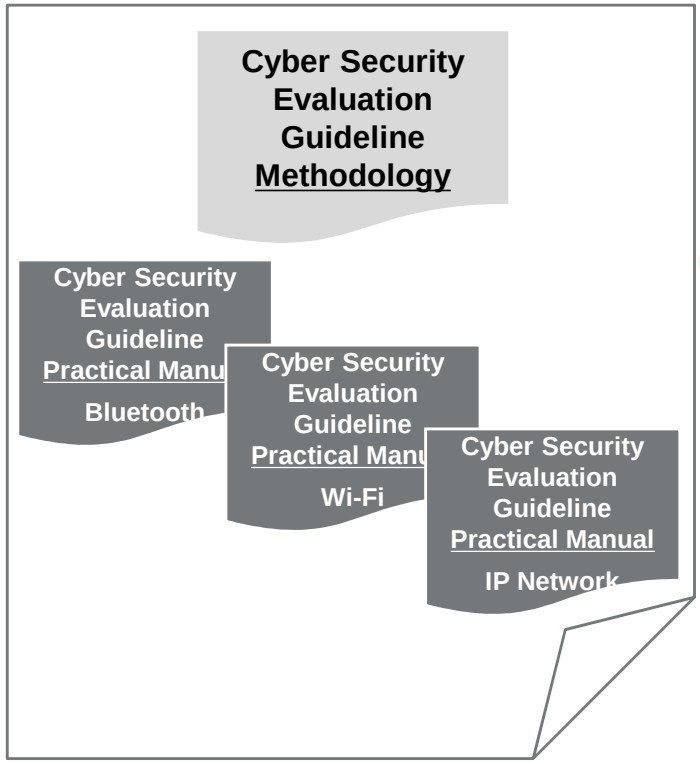
Pre-FOT of information security evaluation

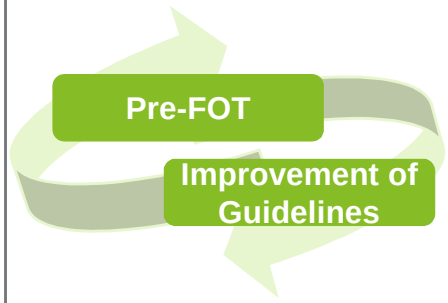
Purpose of Pre-FOT of information security evaluation

Improving effectiveness and usability of Cyber Security Evaluation Guidelines from pre-FOT

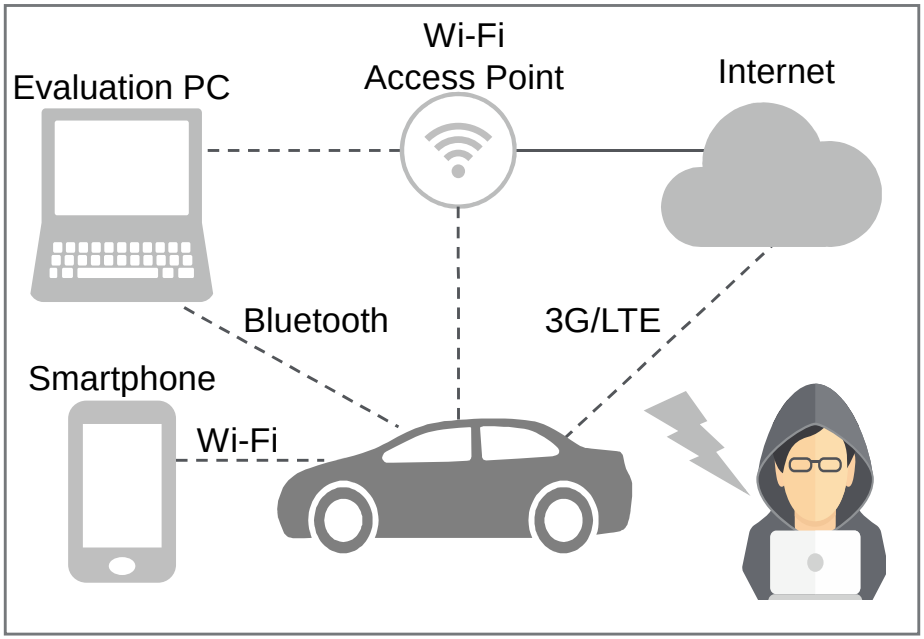
Purpose	■ To verify the validity of the drafted Cyber Security Evaluation Guidelines by conducting a penetration test on vehicle systems ■ To improve the Evaluation Guidelines from the pre-FOT

Evaluation Guideline - DRAFT -





Execution of Pre-FOT in accordance with Evaluation Guideline - DRAFT -



Procedures of pre-FOT

The scope and efficacy of the draft evaluation guidelines are inspected by undertaking a pre-FOT based on the guidelines

	Evaluation flow	Outline
Evaluation process before testing	1 Preparation	➢ Coordinate with participating companies on the various terms to be agreed on
	2 Attacker profiling	➢ Define and profile possible attackers of the vehicles to be evaluated
	3 Identification of targeted components	➢ After specifying the functions (information) that could be targeted by the attackers, map the components of said functions and specify the components susceptible to attacks
	4 Risk analysis for the vehicle	➢ Evaluate component risk based on the threat agent, vulnerability, and impact factors
	5 Evaluation planning	➢ After scoping the testing target, conduct a detailed technical analysis of the relevant components and draw up an evaluation plan
During testing	6 Testing	➢ Conduct testing in accordance with the test plan
Evaluation process after testing	7 Risk mapping	➢ Conduct a risk evaluation of the vulnerabilities found during the testing process
	8 Review of corrective measures and residual risk	➢ Use the results of the risk evaluation to clarify the corrective measures required to each risk, and review residual risk after said measures have been taken
	9 Development of an evaluation report	➢ Explain and report the results of the evaluation to the relevant parties

The evaluation guidelines are to be improved based on the results of the pre-FOT

Confirmation of the validity of the drafted evaluation guidelines and pre-FOT reporting

Confirming the validity of the draft evaluation guidelines

Validity confirmation checklist

- Confirmation of validity is based on the seven strengths and advantages of the evaluation guidelines
  - Usability
    - Confirm that the guidelines can be applied to vehicles already on the market
  - Efficiency
    - Confirm that evaluation can be completed within a realistic timeframe
  - Reproducibility
    - By employing quantitative evaluation, confirm that the results of evaluation can be reproduced
  - Effectiveness
    - Secure the efficacy of the guidelines by providing feedback and making corrections based on issues identified during the evaluation process
  - Sufficiency
    - Confirm that the evaluation guidelines can detect vulnerabilities
  - Specificity
    - Confirm that the content of the guidelines can be understood by testers with a standard skill level
  - Expandability
    - Confirm that there is no repetition in the practical guide, and that the scope of the guidelines can be expanded by adding I/F protocols

Producing a pre-FOT report based on the drafted evaluation guidelines

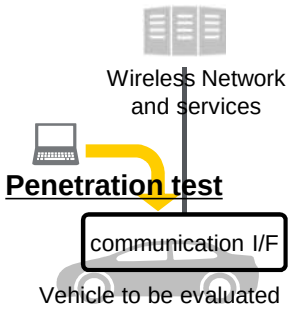
Pre-FOT report on information security evaluation (excerpt of contents)

Preparation for the FOT in FY 2018

Background and aims of the field operational test

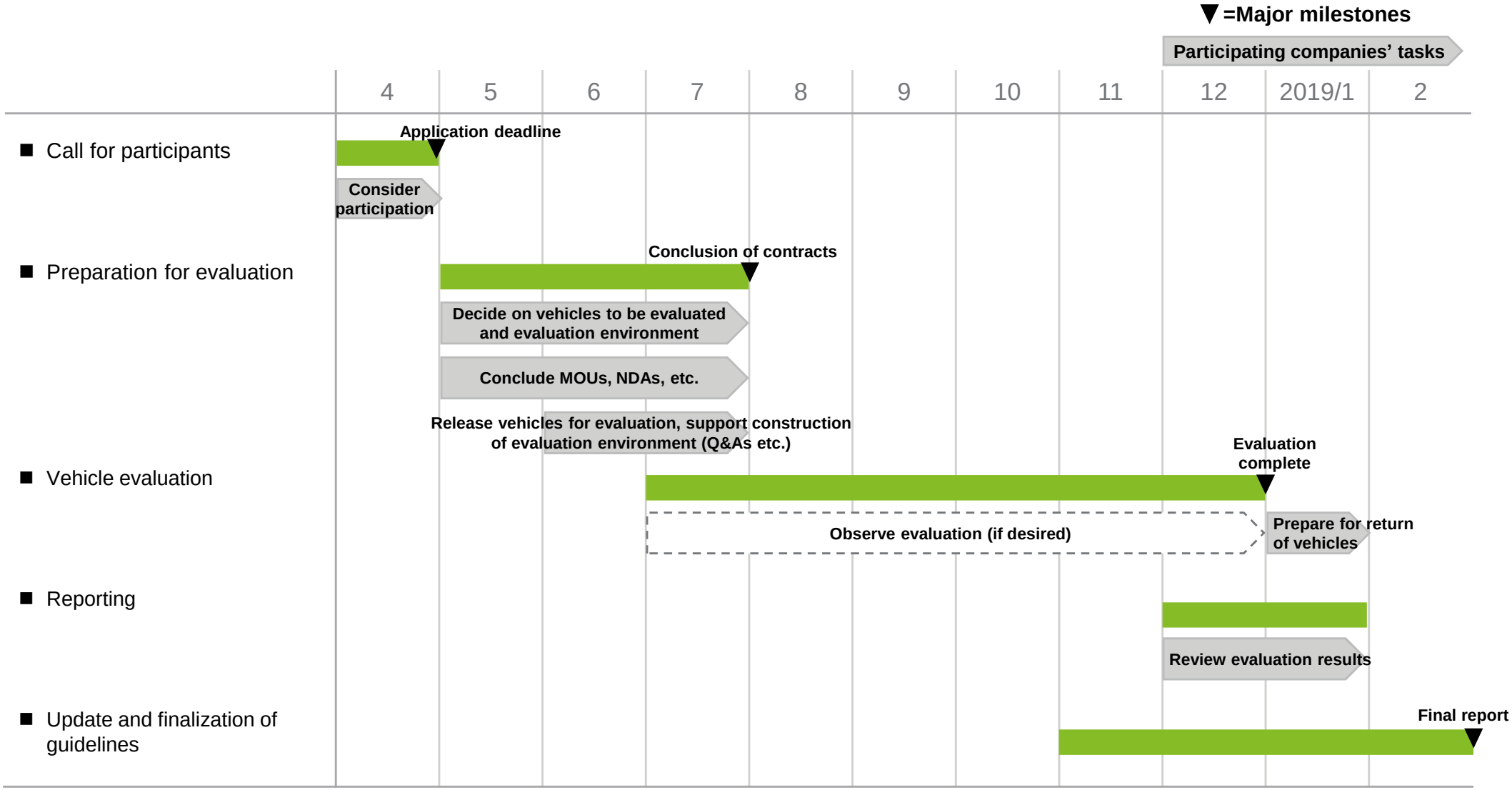
The FOT is conducted to establish a method for evaluating wireless network-based attacks on vehicles

Background	■ Toward the 2020 Tokyo Olympic and Paralympic Games, it is important to accelerate the practical realization of automated driving systems ■ Involving auto manufacturers and other parties, it is necessary to conduct a large-scale FOT focusing on five sectors of technology (dynamic maps, HMI, information security, reduction of pedestrian accidents, and next-generation urban transport) and, with a view to practical realization going forward, highlight specific issues in areas including technology, operations, and systems
Aims	■ By developing vehicle- and component-level security evaluation methods and protocols in the form of guidelines, and conducting black box experiments testing resistance to hacking by using vehicles provided by those participating in this FOT, establish **a method for evaluating wireless network-based attacks on vehicles**



Overall schedule for the field operational test

Recruitment of participating companies will be done in April, evaluation will begin in July after each company's preparations are complete, and the evaluation process is expected to be finished by the end of December



Note: The above schedule is based on assumption on the most effective progress, but actual tasks can be adjusted based on participants' needs

Requirements related to the vehicles to be evaluated and the evaluation environment (1/2)

Participating companies need to agree on various requirements related to the provision of vehicles for evaluation

The following is based on current assumptions, with details set to be adjusted with each company after entry into the project

■ On the provision of vehicles for evaluation

Vehicle requirements	Please prepare a system with at least one of the following wireless network functions: **Wi-Fi**, **Bluetooth**, **3G/4G/LTE**
Vehicle types	Vehicles to be evaluated are assumed to be either **development vehicles or commercially available vehicles**.
Form of vehicle provision	If it is difficult to provide an **actual vehicle**, a **test bench (parts system)** will be accepted. However, the system needs to fulfill the “Vehicle requirements” above and the wireless network communications needs to be testable.
Time of provision	We are looking at a **6-month period.** (The actual time of evaluation is expected to be 2-3 months per vehicle, but because multiple vehicles are being evaluated simultaneously, we would prefer the leeway afforded by a 6-month period. In case a shorter period is required, this can be adjusted individually.)
Spare parts	In addition to one vehicle for evaluation, please provide **spare parts (parts systems including the head unit required for evaluation)*** for the vehicle in question. *Please provide at least one unit. Provision of two or more units will allow for more in-depth evaluation.

Requirements related to the vehicles to be evaluated and the evaluation environment (2/2)

Participating companies need to agree on various requirements related to the provision of vehicles for evaluation

The following is based on current assumptions, with details set to be adjusted with each company after entry into the project

■ On the provision of vehicles for evaluation (continued)

Maintenance support	If problems occur during the construction of the evaluation environment or during evaluation, please be prepared to offer **maintenance support** for the vehicles being evaluated. (Concrete measures include the establishment of a point of contact and coordinating with the suppliers of relevant parts.)
Cost of vehicle provision	**Each participating company will be responsible for the costs of vehicle provision (assumed to include the vehicle itself, transport costs, and spare parts).** We will bear all other related costs (manuals etc.).
Status of vehicles at the time of return	Please be aware that vehicles may be damaged during the evaluation process, and that they will be returned as is.

■ On the preparation of the evaluation environment

External transmission environment	Please prepare the **network services and servers** necessary for telematics. The servers should be running a **test environment** for verification or similar purposes (please also prepare test accounts). In addition, we would appreciate the connections between the vehicles and servers having been tested before vehicle provision.
Information provision	We would appreciate provision of **user and service manuals** (with the same scope of information provided to general users) for the vehicles (we will bear the costs for these).
Consent	Consent for evaluation of vehicles and servers by way of simulated cyberattacks is earned by exchanging memorandums of understanding, non-disclosure agreements, and letters of confirmation (described later).

About information security management

As some of the information handled during the FOT is extremely sensitive, thorough measures must be taken to ensure security

Security measures for preventing information leaks when cooperating with overseas group companies

The below measures are to be taken to prevent leakage of classified information at oversea group companies.

1. Minimize the amount of information available to team members outside of Japan

The following measures are to be taken to minimize the amount of information related to the project available to team members outside of Japan:

- Evaluation is to be conducted only within Japan
- Team members outside of Japan are to take part only as advisors, and may not conduct actual evaluation work
  (Team members outside of Japan should only be given the information required in order for them to share their knowhow and knowledge)

In addition

2. Take contractual measures to prevent information leaks to external parties by team members outside of Japan

The security of classified information related to the project and available to team members of overseas group companies is to be guaranteed by including a confidentiality clause in the contract between the Japanese party and the group companies.

Securing evaluation-related information among participating companies

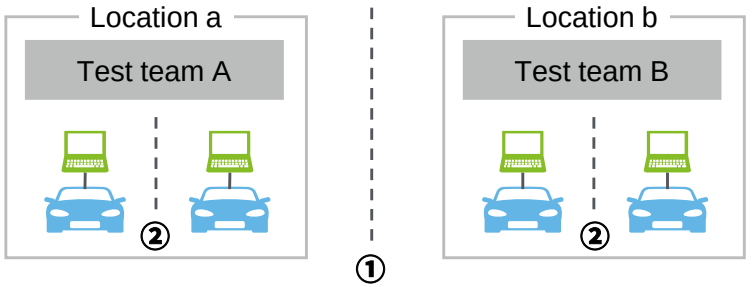
Security is to be ensured by physically dividing evaluation environments.

1. Physical separation of evaluation sites

Security between evaluation sites is to be ensured by conducting evaluation at two separate sites (each one with separate evaluation teams conducting the evaluation) and by not moving evaluation vehicles between the two sites.

2. Physical division of the testing environment

When several vehicles are being evaluated at the same site, the testing environments (including PCs used for evaluation and other equipment) are to be physically separated from each other to ensure security.



In addition to the above, as evidenced by having obtained the international ISO/IEC27001 information security management certificate, our information security management conforms to the international standard, and sufficient security measures will be taken with regard to this project

Scope of disclosing evaluation results

Vehicle-specific evaluation results, items, and procedures are to be disclosed only to the participating companies

■ As stipulated in the non-disclosure agreement concluded between each participating company and NEDO, vehicle-specific evaluation results are to be disclosed only to the relevant participating company.

Legend O: Can be disclosed
X: Cannot be disclosed

Type of information		Scope of disclosure		
		Provider of evaluation vehicle (participating company)	Managing entity of the FOT (NEDO)	The public (in guidelines etc.)
1	Vehicle-specific evaluation results	○	×	×
2	Vehicle-specific evaluation items and procedures	○	△[2]	×
3	Statistical[1] evaluation results	○	○	○
4	Generalized evaluation items and procedures	○	○	○

1 “Statistical” here refers to evaluation data for multiple vehicles which has been formatted to express qualities and tendencies in quantitative form, and which cannot be used to identify any of the participating companies.

2 Disclosure within the limits consented to by the participating companies.